

# Haarove temeljne funkcije

---

## Haarove temeljne funkcije

### Temeljne funkcije:

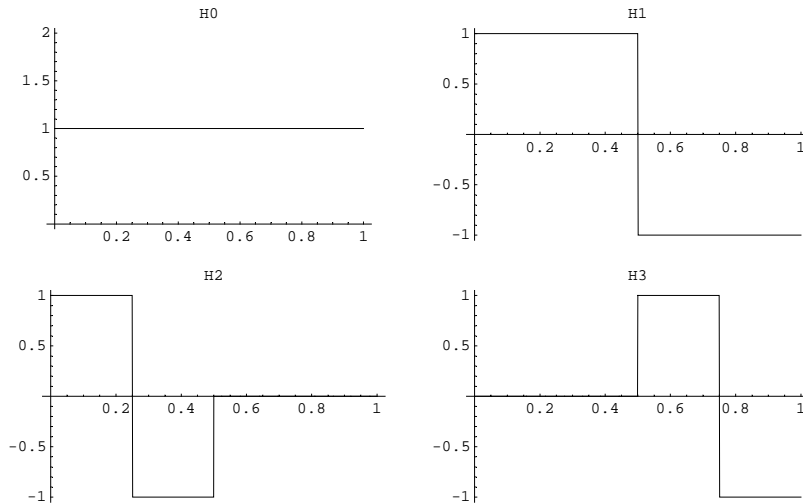
```
In[131]:= H0[t_] := 1;
          H1[t_] := Which[t ≥ 0 && t ≤ 1/2, 1,
                        t > 1/2 && t ≤ 1, -1,
                        t < 0 || t > 1, 0];
          H2[t_] := Which[t ≥ 0 && t ≤ 1/4, 1,
                        t > 1/4 && t ≤ 1/2, -1,
                        t > 1/2 && t ≤ 1, 0,
                        t < 0 || t > 1, 0];
          H3[t_] := Which[t ≥ 1/2 && t ≤ 3/4, 1,
                        t > 3/4 && t ≤ 1, -1,
                        t ≥ 0 && t < 1/2, 0,
                        t < 0 || t > 1, 0];
```

### Koeficienti:

```
In[91]:= K0 := 1;
          K1 := 1;
          K2 :=  $\frac{1}{2}$ ;
          K3 :=  $\frac{1}{2}$ ;
```

### Izris funkcij:

```
In[95]:= << Graphics`Graphics`
DisplayTogetherArray[{{
  Plot[H0[t], {t, 0, 1}, PlotRange → All, PlotLabel → "H0"],
  Plot[H1[t], {t, 0, 1}, PlotRange → All, PlotLabel → "H1"]},
{Plot[H2[t], {t, 0, 1}, PlotRange → All, PlotLabel → "H2"],
  Plot[H3[t], {t, 0, 1}, PlotRange → All, PlotLabel → "H3"]}]]
```



```
Out[96]= - GraphicsArray -
```

## Aproksimacija signala na osnovnem intervalu (naloga 1)

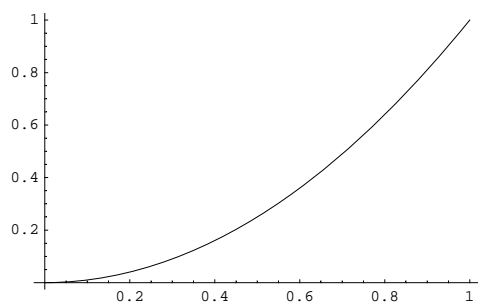
**Naloga 1:** Signal  $x(t) = t^2$  na intervalu  $[0,1]$  izrazite s približkom prvih štirih Haarovih temeljnih funkcij.

Določite še napako aproksimacije in skicirajte približek.

### Rešitev:

```
In[97]:= x[t_] := t2;
```

```
In[98]:= Plot[x[t], {t, 0, 1}, PlotRange → All];
```



Izračun koeficientov:

```
In[99]:= c0 =  $\frac{1}{1} * \int_0^1 t^2 * 1 dt$ 
```

```
Out[99]=  $\frac{1}{3}$ 
```

$$\text{In}[100]:= \mathbf{C1} = \frac{1}{1} * \left( \int_0^{1/2} t^2 * 1 \, dt + \int_{1/2}^1 t^2 * (-1) \, dt \right)$$

$$\text{Out}[100]= -\frac{1}{4}$$

$$\text{In}[101]:= \mathbf{C2} = \frac{1}{\frac{1}{2}} * \left( \int_0^{1/4} t^2 * 1 \, dt + \int_{1/4}^{1/2} t^2 * (-1) \, dt \right)$$

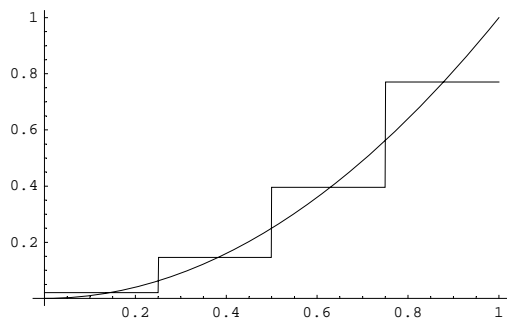
$$\text{Out}[101]= -\frac{1}{16}$$

$$\text{In}[102]:= \mathbf{C3} = \frac{1}{\frac{1}{2}} * \left( \int_{1/2}^{3/4} t^2 * 1 \, dt + \int_{3/4}^1 t^2 * (-1) \, dt \right)$$

$$\text{Out}[102]= -\frac{3}{16}$$

Izris aproksimiranega signala:

`In[103]:= Plot[{C0 * H0[t] + C1 * H1[t] + C2 * H2[t] + C3 * H3[t], x[t]}, {t, 0, 1}`



Izračun napake:

`In[104]:= T = 1;`

$$\epsilon = \frac{1}{T} * \left( \int_0^1 t^2 * t^2 \, dt - (K0 * C0^2 + K1 * C1^2 + K2 * C2^2 + K3 * C3^2) \right)$$

$$\text{Out}[105]= \frac{79}{11520}$$

`In[106]:= N[%]`

$$\text{Out}[106]= 0.00685764$$

## Aproksimacija signala na drugem intervalu (naloga 2)

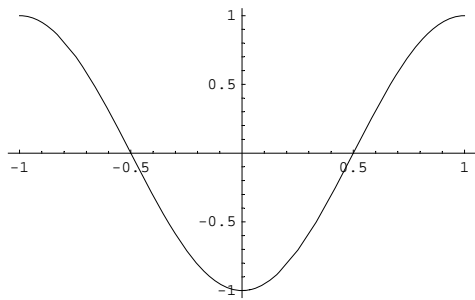
**Naloga 2:** Signal  $x(t) = -\cos[\pi t]$  na intervalu  $[-1,1]$  izrazite s približkom prvih štirih Haarovih temeljnih funkcij.

Določite še razliko v napaki aproksimacije, če aproksimiramo s prvimi štirimi Haarovimi funkcijami ali samo s prvimi tremi Haarovimi funkcijami.

**Rešitev:**

`In[108]:= x[t_] := -Cos[π * t];`

```
In[109]:= Plot[x[t], {t, -1, 1}, PlotRange -> All];
```



Haarove funkcije imamo definirane na intervalu  $[0,1]$  zato jih moramo premakr in izvajati aproksimacijo s premaknjenimi Haarovimi t.f.

*Premaknjene Haarove. t.f.*

Poiščemo preslikavo  $\mathbf{u}: [-1,1] \rightarrow [0,1]$ ;  $\mathbf{u}[t] = \mathbf{a} * t + \mathbf{b}$

```
In[110]:= u[t_] := 1/2 * t + 1/2;
```

```
In[111]:= H0[t_] := H0[u[t]];
H1[t_] := H1[u[t]];
H2[t_] := H2[u[t]];
H3[t_] := H3[u[t]];
```

$$\mathbf{a} = \frac{1}{2};$$

$$\hat{\mathbf{K}}_0 := \frac{\mathbf{K}_0}{\mathbf{a}}$$

$$\hat{\mathbf{K}}_1 := \frac{\mathbf{K}_1}{\mathbf{a}}$$

$$\hat{\mathbf{K}}_2 := \frac{\mathbf{K}_2}{\mathbf{a}}$$

$$\hat{\mathbf{K}}_3 := \frac{\mathbf{K}_3}{\mathbf{a}}$$

```
In[120]:= {K0, K1, K2, K3}
```

```
Out[120]= {2, 2, 1, 1}
```

*Izračun koeficientov*

```
In[121]:= c0 = 1/K0 * Integrate[x[t] * H0[t], {t, -1, 1}]
```

```
Out[121]= 0
```

$$\text{In[122]:= } \mathbf{C1} = \frac{1}{\hat{K1}} * \int_{-1}^1 \mathbf{x}[t] * \hat{H1}[t] dt$$

$$\text{Out[122]= } 0$$

$$\text{In[123]:= } \mathbf{C2} = \frac{1}{\hat{K2}} * \int_{-1}^1 \mathbf{x}[t] * \hat{H2}[t] dt$$

$$\text{Out[123]= } \frac{2}{\pi}$$

$$\text{In[124]:= } \mathbf{C3} = \frac{1}{\hat{K3}} * \int_{-1}^1 \mathbf{x}[t] * \hat{H3}[t] dt$$

$$\text{Out[124]= } -\frac{2}{\pi}$$

Pomoč pri izračunu koeficientov C2 in C3 :

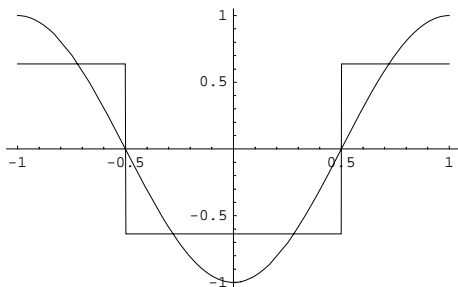
$$\text{In[74]:= } \int \cos[\pi * t] dt = \frac{\sin[\pi t]}{\pi}$$

$$\text{In[125]:=}$$

$$\text{In[126]:=}$$

*Izračun aproksimiranega signala:*

$$\text{In[127]:= } \text{Plot} \left[ \left\{ \mathbf{C0} * \hat{H0}[t] + \mathbf{C1} * \hat{H1}[t] + \mathbf{C2} * \hat{H2}[t] + \mathbf{C3} * \hat{H3}[t], \mathbf{x}[t] \right\}, \right. \\ \left. \{t, -1, 1\} \right];$$



$$\text{In[128]:=}$$

*Izračun razlike napake, če aproksimiramo s prvimi 4-imi H.t.f. ali pa samo s 3-mi*

$$\text{In[77]:=}$$

$$\Delta \epsilon = \epsilon_4 - \epsilon_3 = \frac{1}{t_2 - t_1} * K_3 * C_3 * C_3;$$

*V našem primeru:*

$$\text{In[129]:= } \Delta \epsilon = \frac{1}{2} * \left( -\frac{2}{\pi} \right) * \left( -\frac{2}{\pi} \right)$$

$$\text{Out[129]= } \frac{2}{\pi^2}$$

In[130]:= **N**[%]

Out[130]= 0.202642