

Izražava signalov s temeljnimi funkcijami

Walsheve temeljne funkcije

Definicija prvih štirih funkcij

In[32]:=

$$W_0[t_] := \begin{cases} 1 & 0 \leq t \leq 1 \\ 0 & \text{True} \end{cases}$$

$$W_1[t_] := \begin{cases} 1 & 0 < t \leq \frac{1}{2} \\ -1 & \frac{1}{2} < t \leq 1 \\ 0 & \text{True} \end{cases}$$

$$W_2[t_] := \begin{cases} 1 & 0 < t \leq \frac{1}{4} \\ -1 & \frac{1}{4} < t \leq \frac{1}{2} \\ 1 & \frac{1}{2} < t \leq \frac{3}{4} \\ -1 & \frac{3}{4} < t \leq 1 \\ 0 & \text{True} \end{cases}$$

$$W_3[t_] := \begin{cases} 1 & 0 < t \leq \frac{1}{4} \\ -1 & \frac{1}{4} < t \leq \frac{3}{4} \\ 1 & \frac{3}{4} < t \leq 1 \\ 0 & \text{True} \end{cases}$$

Koeficienti:

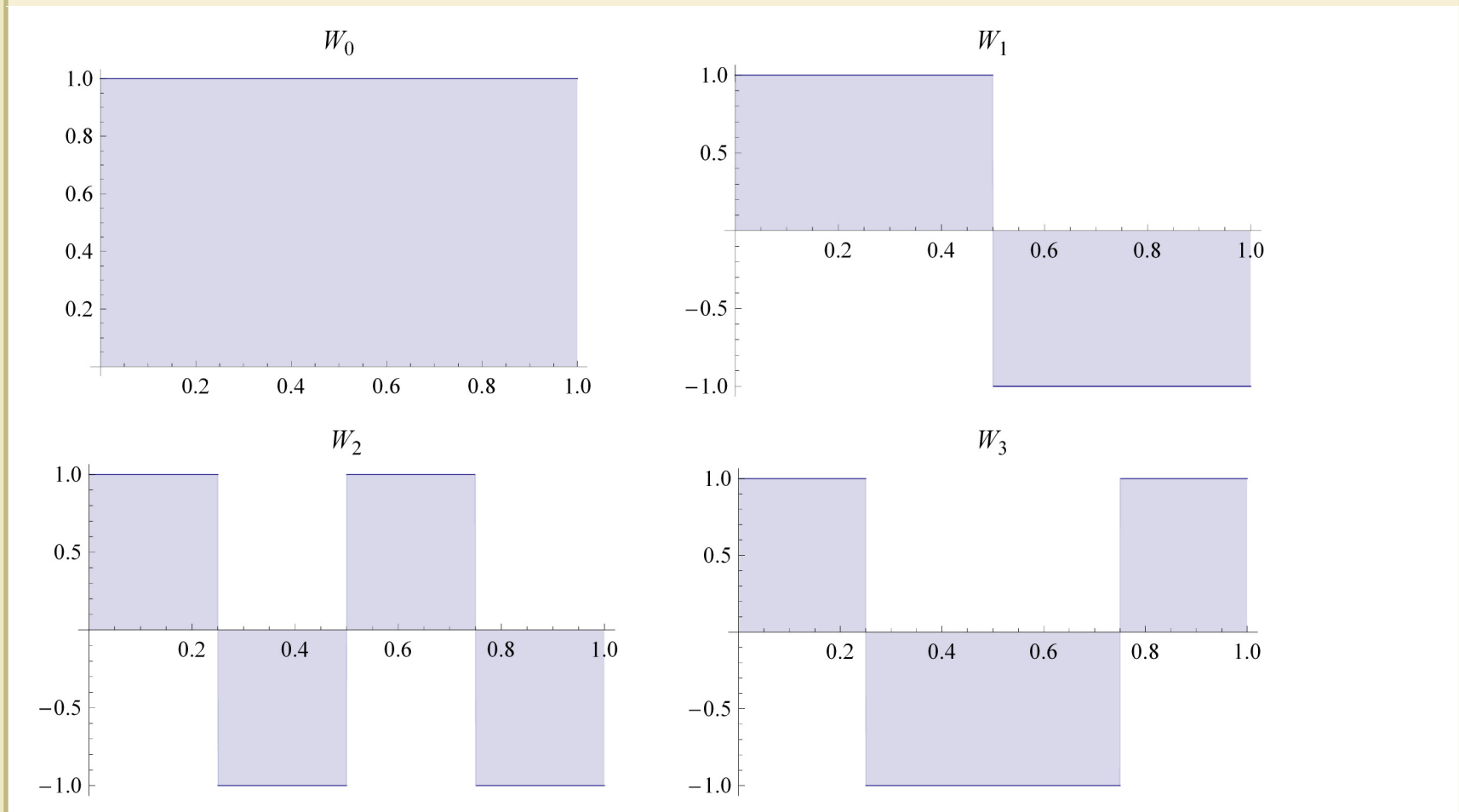
In[36]:=

$$\begin{aligned} K_0 &:= 1; \\ K_1 &:= 1; \\ K_2 &:= 1; \\ K_3 &:= 1; \end{aligned}$$

Izris funkcij:

```
In[40]:= gw0 = Plot[W0[t], {t, 0, 1}, PlotRange -> All, PlotLabel -> "W0", Filling -> Axis];
gw1 = Plot[W1[t], {t, 0, 1}, PlotRange -> All, PlotLabel -> "W1", Filling -> Axis];
gw2 = Plot[W2[t], {t, 0, 1}, PlotRange -> All, PlotLabel -> "W2", Filling -> Axis];
gw3 = Plot[W3[t], {t, 0, 1}, PlotRange -> All, PlotLabel -> "W3", Filling -> Axis];
GraphicsGrid[{{gw0, gw1}, {gw2, gw3}}]
```

Out[44]=



Aproksimacija signala (naloga)

Naloga:

Signal $x(t) = t^2$ na intervalu $[0,1]$ izrazite s približkom prvih štirih Walshevih temeljnih funkcij.

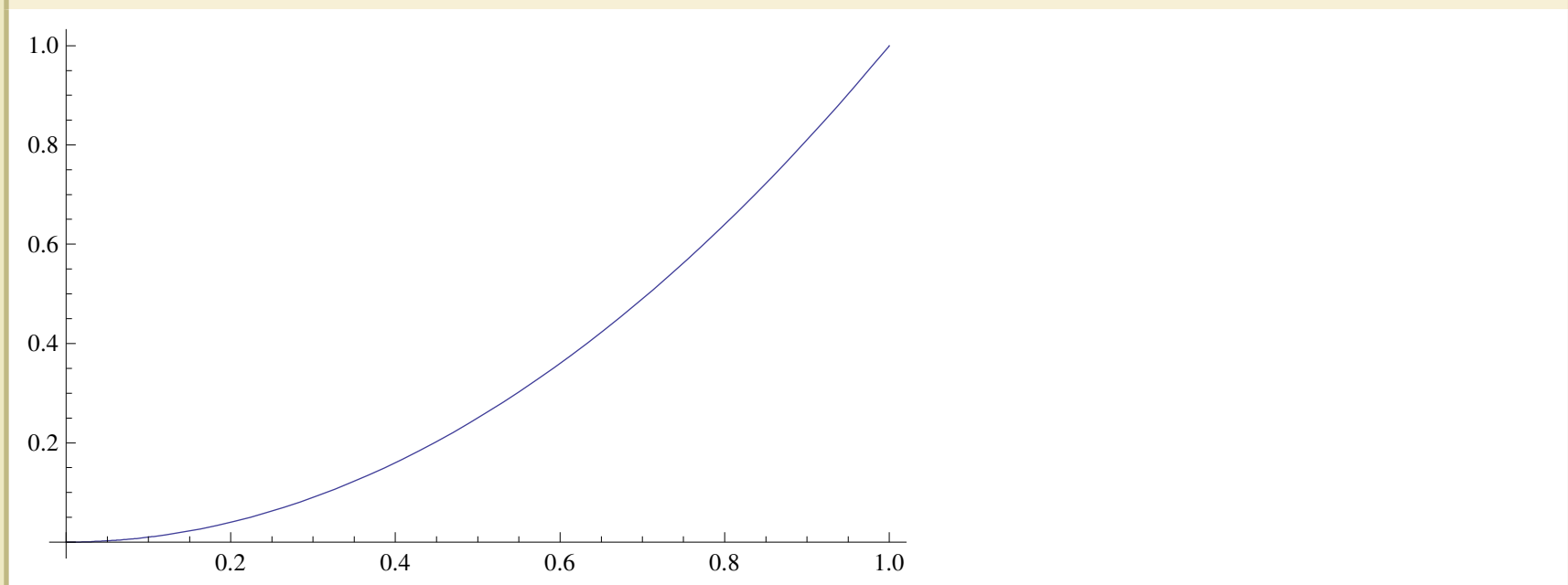
Določite še napako aproksimacije in skicirajte približek.

Rešitev:

```
In[45]:= x[t_] := t^2;
```

```
In[46]:= Plot[x[t], {t, 0, 1}, PlotRange -> All]
```

Out[46]=

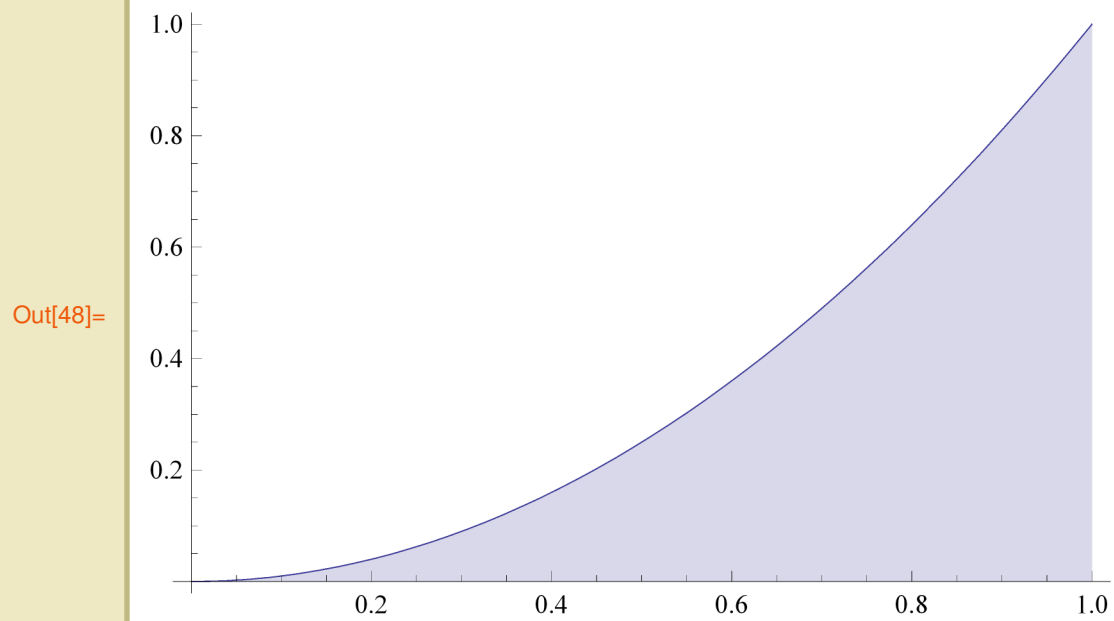


Izračun koeficientov:

In[47]:=
$$C_0 = \frac{1}{1} * \int_0^1 t^2 * 1 dt$$

Out[47]=
$$\frac{1}{3}$$

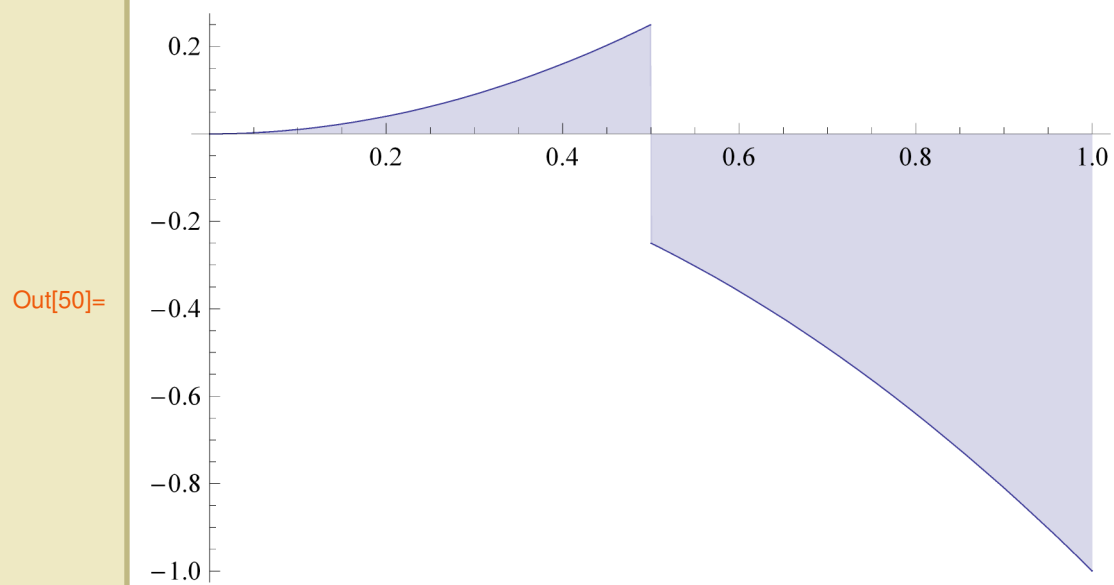
In[48]:= `Plot[{x[t] * W0[t]}, {t, 0, 1}, Filling -> Axis]`



In[49]:=
$$C_1 = \frac{1}{1} * \left(\int_0^{1/2} t^2 * 1 dt + \int_{1/2}^1 t^2 * (-1) dt \right)$$

Out[49]=
$$-\frac{1}{4}$$

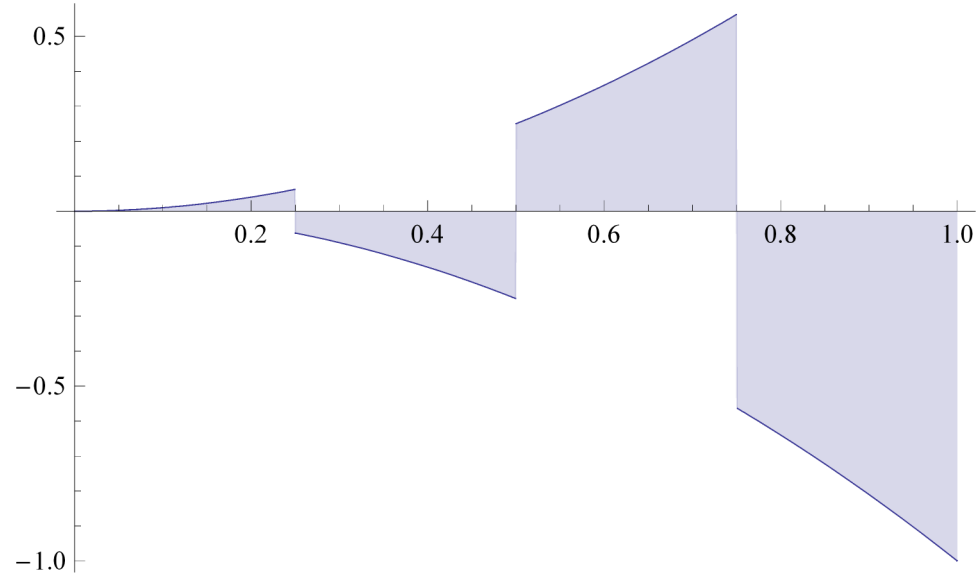
In[50]:= `Plot[{x[t] * W1[t]}, {t, 0, 1}, Filling -> Axis]`



In[52]:=
$$C_2 = \frac{1}{1} * \left(\int_0^{1/4} t^2 * 1 dt + \int_{1/4}^{1/2} t^2 * (-1) dt + \int_{1/2}^{3/4} t^2 * 1 dt + \int_{3/4}^1 t^2 * (-1) dt \right)$$

Out[52]=
$$-\frac{1}{8}$$

In[54]:= `Plot[{x[t] * W2[t]}, {t, 0, 1}, Filling -> Axis]`

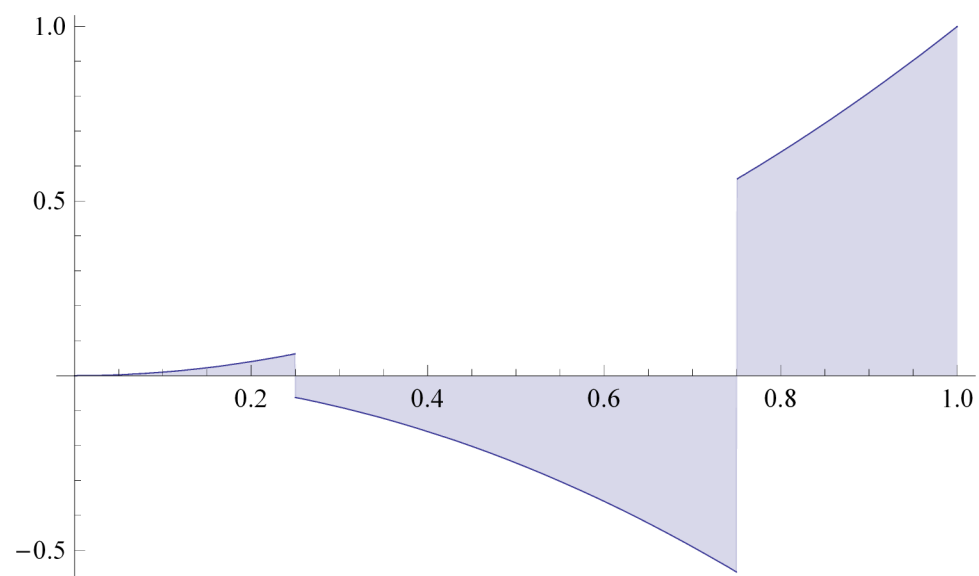


Out[54]=

In[53]:=
$$C_3 = \frac{1}{1} * \left(\int_0^{1/4} t^2 * 1 dt + \int_{1/4}^{3/4} t^2 * (-1) dt + \int_{3/4}^1 t^2 * 1 dt \right)$$

Out[53]=
$$\frac{1}{16}$$

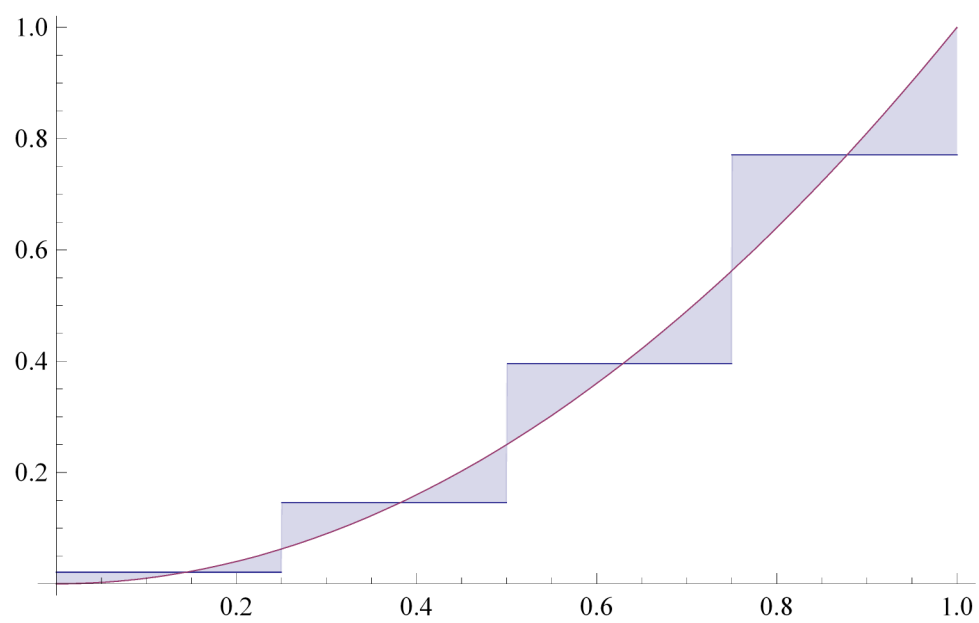
In[55]:= `Plot[{x[t] * W3[t]}, {t, 0, 1}, Filling -> Axis]`



Out[55]=

Izris aproksimiranega signala:

In[62]:= `Plot[{C0 W0[t] + C1 W1[t] + C2 W2[t] + C3 W3[t], x[t]}, {t, 0, 1}, Filling -> {1 -> {2}}]`



Out[62]=

Izračun napake:

In[57]:=

 $t_1 = 0;$ $t_2 = 1;$

$$\epsilon = \frac{1}{t_2 - t_1} * \left(\int_0^1 t^2 * t^2 dt - (K_0 * C_0^2 + K_1 * C_1^2 + K_2 * C_2^2 + K_3 * C_3^2) \right)$$

Out[59]=

$$\frac{79}{11520}$$

In[60]:=

N[%]

Out[60]=

0.00685764