

# PROCESIRANJE SIGNALOV

Datum: 02. 02. 2007

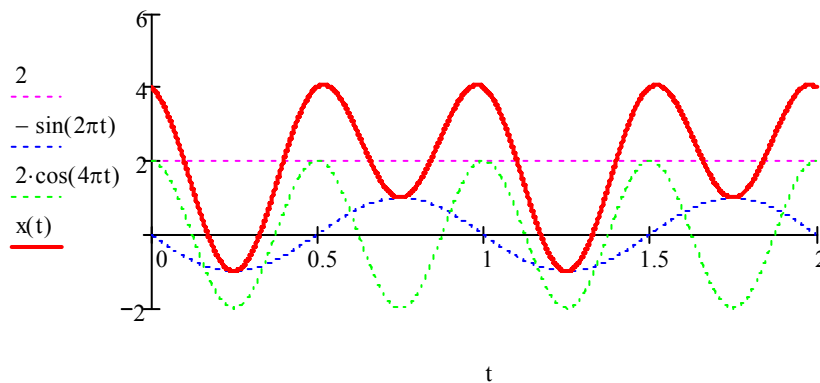
1. Narišite skico in določite Fourierovo vrsto signala

$$x(t) = 2 - \sin(2\pi t) + 2 \cos(4\pi t)$$

Koliko znaša  $X_0$ ? Ali je signal močnostni ali energijski?

*Nasvet: Zapišite vrsto  $a_n, b_n$ .*

Rešitev:



$$x(t) = a_0 + \sum_{n=1}^{\infty} (a_n \cos(n\omega_0 t) + b_n \sin(n\omega_0 t)) \quad (1.1)$$

$$\omega_0 = 2\pi \quad (1.2)$$

$$x(t) = a_0 + a_1 \cos(2\pi t) + b_1 \sin(2\pi t) + a_2 \cos(4\pi t) + b_2 \sin(4\pi t) + a_3 \cos(6\pi t) + b_3 \sin(6\pi t) + \dots \quad (1.3)$$

$$a_0 = X_0 = 2 \quad (1.4)$$

$$b_1 = -1 \quad (1.5)$$

$$a_2 = 2 \quad (1.6)$$

$$a_n = 0 \quad ; \quad n \neq 0, n \neq 2 \quad (1.7)$$

$$b_n = 0 \quad ; \quad n \neq 1 \quad (1.8)$$

2. Podan je odziv linearnega, časovno nespremenljivega sistema:

$$h(t) = \begin{cases} 2 & ; 0 < t < 3 \\ 0 & ; \text{sicer} \end{cases}$$

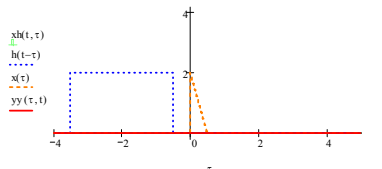
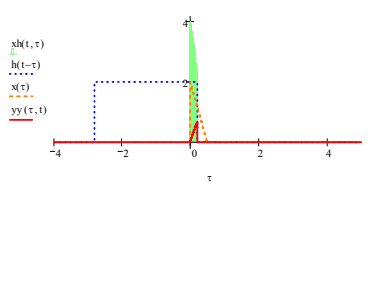
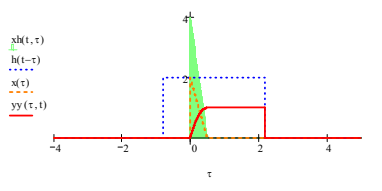
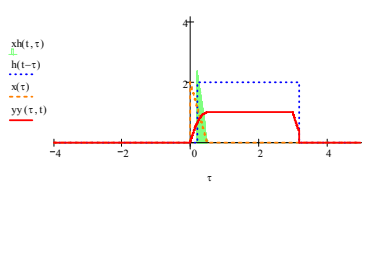
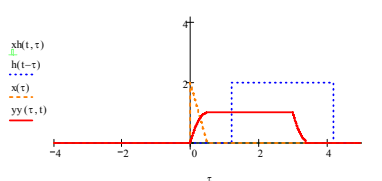
Izračunajte in narišite odziv  $y(t)$  takšnega sistema na vzbujanje

$$x(t) = \begin{cases} 2-4t & ; 0 < t < 0,5 \\ 0 & ; \text{sicer} \end{cases}$$

Rešitev:

$$y(t) = \int_0^t x(\tau)h(t-\tau)d\tau = \int_0^t x(t-\tau)h(\tau)d\tau \quad (2.1)$$

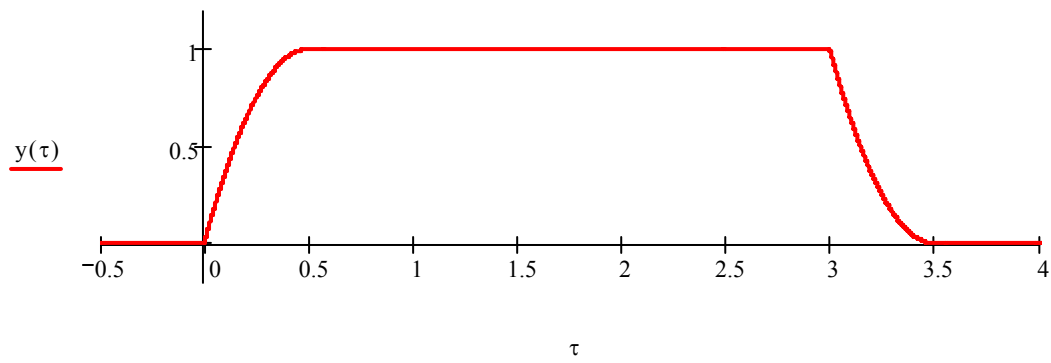
V tem primeru laže obrniti  $h(t)$ . Zato bomo uporabili prvo enačbo.

$t < 0$		$y(t) = 0 \quad (2.2)$
$0 < t < 0,5$		$\begin{aligned} y(t) &= \int_0^t 2 \cdot (2-4\tau) d\tau = \\ &= 4 \int_0^t d\tau - 8 \int_0^t \tau d\tau = \\ &= 4\tau \Big _0^t - 8 \frac{\tau^2}{2} \Big _0^t = 4t - 4t^2 \end{aligned} \quad (2.3)$
$0,5 < t < 3$		$\begin{aligned} y(t) &= \int_0^{0,5} 2 \cdot (2-4\tau) d\tau = \\ &= 4\tau \Big _0^{0,5} - 8 \frac{\tau^2}{2} \Big _0^{0,5} = 2 - 1 = 1 \end{aligned} \quad (2.4)$
$3 < t < 3,5$		$\begin{aligned} y(t) &= \int_{t-3}^{0,5} 2 \cdot (2-4\tau) d\tau = 4\tau \Big _{t-3}^{0,5} - 8 \frac{\tau^2}{2} \Big _{t-3}^{0,5} = \\ &= 4(0,5 - t + 3 - (0,5^2 - t^2 + 6t - 9)) = \\ &= 14 - 4t + 4t^2 - 24t + 35 = \\ &= 4t^2 - 28t + 49 \end{aligned} \quad (2.5)$
$3,5 < t$		$y(t) = 0 \quad (2.6)$

Združimo vse delne rezultate v končni rezultat:

$$y(t) = \begin{cases} -4t^2 + 4t & ; 0 < t < 0,5 \\ 1 & ; 0,5 < t < 3 \\ 4t^2 - 28t + 49 & ; 3 < t < 3,5 \\ 0 & ; \text{ sicer} \end{cases} \quad (2.7)$$

Skica:



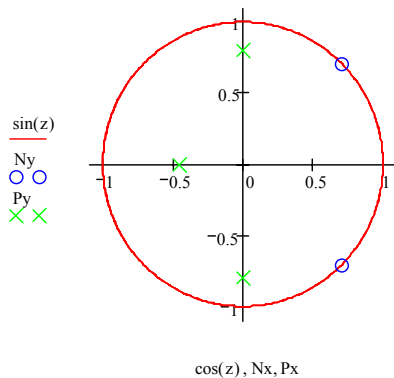
3. Časovno diskretni sistem je podan z ničlami in poli:

$$n_{1,2} = \frac{\sqrt{2}}{2} \pm j \frac{\sqrt{2}}{2}, \quad p_{1,2} = \pm j0,8, \quad p_3 = -0,45$$

Narišite lego ničel in polov v z-ravnini. Ali je podano časovno diskretno linearno vezje stabilno? Skicirajte potek frekvenčnega odziva  $|H(\Omega)|$ ! Določite sistemsko funkcijo  $H(z)$ , zapišite diferenčno enačbo in narišite shemo vezja.

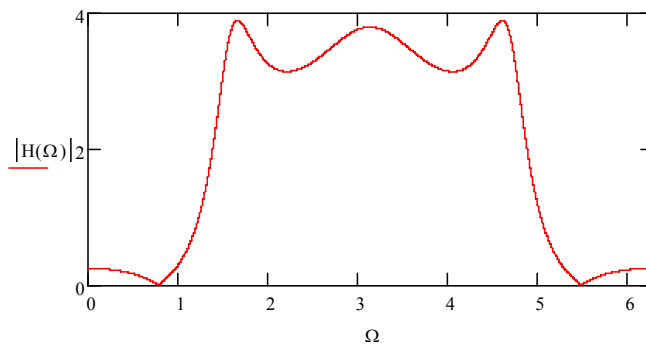
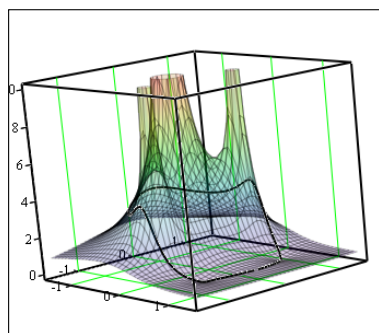
Rešitev:

Legra ničel in polov v z-ravnini:



Vezje je stabilno, ker so vsi poli znotraj enotske krožnice.

3D slika z-ravnine in skica frekvenčnega odziva:



Sistemska funkcija  $H(z)$ :

$$H(z) = \frac{(z - n_1)(z - n_2)}{(z - p_1)(z - p_2)(z - p_3)} \quad (3.1)$$

$$\begin{aligned} H(z) &= \frac{z^2 - (n_1 + n_2)z + n_1n_2}{(z^2 - (p_1 + p_2)z + p_1p_2)(z - p_3)} \\ &= \frac{z^2 - (n_1 + n_2)z + n_1n_2}{z^3 - (p_1 + p_2)z^2 + p_1p_2z - p_3z^2 + p_3(p_1 + p_2)z - p_1p_2p_3} = \\ &= \frac{z^2 - (n_1 + n_2)z + n_1n_2}{z^3 - (p_1 + p_2 + p_3)z^2 + (p_1p_2 + p_1p_3 + p_2p_3)z - p_1p_2p_3} \end{aligned} \quad (3.2)$$

$$-(n_1 + n_2) = -\left(\frac{\sqrt{2}}{2} + j\frac{\sqrt{2}}{2} + \frac{\sqrt{2}}{2} - j\frac{\sqrt{2}}{2}\right) = -\sqrt{2}$$

$$n_1 n_2 = \left(\frac{\sqrt{2}}{2} + j\frac{\sqrt{2}}{2}\right)\left(\frac{\sqrt{2}}{2} - j\frac{\sqrt{2}}{2}\right) = \left(\frac{\sqrt{2}}{2}\right)^2 + \left(\frac{\sqrt{2}}{2}\right)^2 = 1$$

$$-(p_1 + p_2 + p_3) = -(j0,8 - j0,8 - 0,45) = 0,45 \quad (3.3)$$

$$p_1 p_2 + p_1 p_3 + p_2 p_3 = (j0,8)(-j0,8) - 0,45(j0,8) - 0,45(-j0,8) = 0,64$$

$$-p_1 p_2 p_3 = -(j0,8)(-j0,8)(-0,45) = 0,64 \cdot 0,45 = 0,288$$

$$H(z) = \frac{z^2 - \sqrt{2}z + 1}{z^3 + 0,45z^2 + 0,64z + 0,288} = \frac{z^{-1} - \sqrt{2}z^{-2} + z^{-3}}{1 + 0,45z^{-1} + 0,64z^{-2} + 0,288z^{-3}} \quad (3.4)$$

Diferenčna enačba:

$$H(z) = \frac{Y(z)}{X(z)} = \frac{z^{-1} - \sqrt{2}z^{-2} + z^{-3}}{1 + 0,45z^{-1} + 0,64z^{-2} + 0,288z^{-3}} \quad (3.5)$$

$$Y(z)(1 + 0,45z^{-1} + 0,64z^{-2} + 0,288z^{-3}) = X(z)(z^{-1} - \sqrt{2}z^{-2} + z^{-3}) \quad (3.6)$$

$$Y(z) + 0,45Y(z)z^{-1} + 0,64Y(z)z^{-2} + 0,288Y(z)z^{-3} =$$

$$= X(z)z^{-1} - \sqrt{2}X(z)z^{-2} + X(z)z^{-3} \quad (3.7)$$

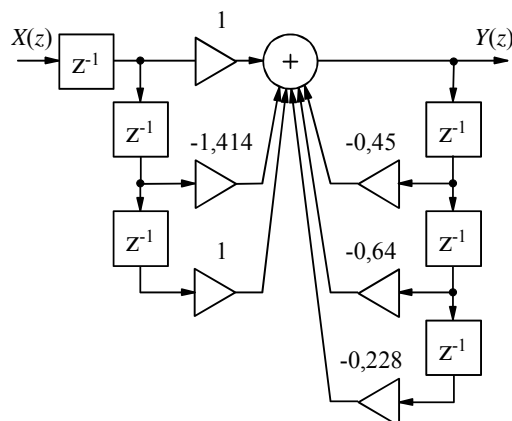
$$Y(z) = X(z)z^{-1} - \sqrt{2}X(z)z^{-2} + X(z)z^{-3} -$$

$$-0,45Y(z)z^{-1} - 0,64Y(z)z^{-2} - 0,288Y(z)z^{-3} \quad (3.8)$$

$$y[n] = x[n-1] - \sqrt{2}x[n-2] + x[n-3]$$

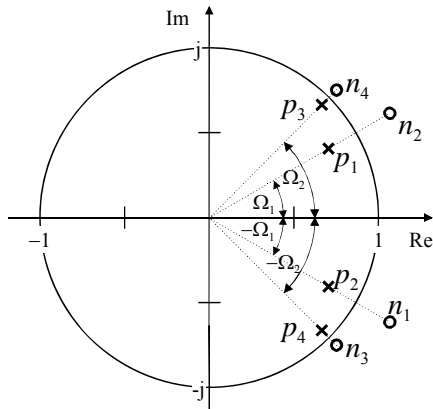
$$-0,45y[n-1] - 0,64y[n-2] - 0,288y[n-3] \quad (3.9)$$

Shema vezja:



#### 4. Teoretična vprašanja

- a) Kakšna mora biti razporeditev polov in ničel časovno diskretnega faznega sukalnika? Ponazorite na primeru sistema 4. reda!



Ničle in poli si morajo biti inverzni.

$$n_i = \frac{1}{p_i}$$

Da je sistem stabilen, morajo biti poli znotraj enotske krožnice. Iz tega sledi, da so ničle na zunanji strani enotske krožnice.

- b) Zapišite vse rešitve enačbe  $z^3 = 1$ !

$$z^3 = 1 = e^{j(0+2k\pi)} \quad (4.1)$$

$$\left(z^3\right)^{\frac{1}{3}} = \left(e^{j2k\pi}\right)^{\frac{1}{3}} \quad (4.2)$$

$$z = e^{\frac{j2k\pi}{3}} \quad (4.3)$$

$$z_1 = e^{\frac{j2 \cdot 0 \cdot \pi}{3}} = 1 \quad (4.4)$$

$$z_2 = e^{\frac{j2 \cdot 1 \cdot \pi}{3}} = -0,5 + j0,866 \quad (4.5)$$

$$z_3 = e^{\frac{j2 \cdot 2 \cdot \pi}{3}} = -0,5 - j0,866 \quad (4.6)$$

- c) Kaj mora veljati za lego ničel in polov stabilnega časovno diskretnega sistema z maksimalno fazo?

Poli morajo biti znotraj enotske krožnice. Ničle morajo biti na zunanji strani enotske krožnice.

- d) Časovno diskreten sistem je podan z ničlami in poli:

$$n_{1,2} = 1, n_{3,4} = e^{\pm j\frac{\pi}{6}}, n_{5,6} = e^{\pm j\frac{\pi}{3}}, p_{1,2} = 0,9e^{\pm j\frac{\pi}{6}}, p_{3,4} = 0,9e^{\pm j\frac{\pi}{3}}$$

Dopolnite ga z ničlami ali poli tako, da bo postal uresničljiv. Pri tem se frekvenčni odziv  $|H(\Omega)|$  ne sme spremeniti.

$$p_{5,6} = 0 \quad (4.7)$$

- e) Napišite Fourierove transforme funkcij:

$$\bullet \quad x(t) = 5 \quad \leftrightarrow \quad X(\omega) = 5 \cdot 2\pi\delta(\omega)$$

$$\bullet \quad x(t) = 2\delta(t) \quad \leftrightarrow \quad X(\omega) = 2$$