

DENOTACIJSKA SEMANTIKA - ZGLEDI

Zgled 1:

Definiraj sintakso in semantiko preprostih boolovih izrazov. V izrazih lahko nastopajo sprem. x , y in z (ki imajo nedefinirano vrednost true ali false), konstante true in false ter operatorji and, or in not.

Nekaj primerov sintakticno pravilnih izrazov:

```
z
x or ( y and not z )
not x and ( true and ( false or y ) )
```

1. Sintakticna domena (v BNF notaciji):

```
<exp> ::=
    <fact> and <exp> | <fact> or <exp> |
    <fact>
<fact> ::=
    true | false | <var>
    not <fact> | ( <exp> )
<var> ::= x | y | z
```

2. Opis stanja in semanticnih funkcij:

State \equiv {true, false} \times {true, false} \times {true, false}

// stanje opisujejo vrednosti sprem. x , y in z

Mexp: exp \rightarrow (State \rightarrow { true, false })

// izraz preslika trenutno stanje sprem. x , y , in z v vrednost izraza true ali false

Mfact: fact \rightarrow (State \rightarrow { true, false })

MVar: Var \rightarrow (State \rightarrow { true, false })

3. Definicija semanticnih funkcij:

Mexp [e:exp] (s:State) \equiv

```
<fact> and <exp> => Mfact[e.fact](s) AND Mexp[e.exp](s) |
<fact> or <exp> => Mfact[e.fact](s) OR Mexp[e.exp](s) |
<fact> => Mfact[e.fact](s)
```

Mfact [f:fact] (s:State) \equiv

```
true => true |
false => false |
<var> => Mvar[f.var](s) |
not <fact> => NOT Mfact[f.fact](s) |
( <exp> ) => Mexp[f.exp](s)
```

Mvar [v:var] (<xVal, yVal, zVal>:State) \equiv

```
x => xVal |
y => yVal |
z => zVal
```

Zgled 2:

Denimo da je vrednost stanja State = <true, true, true>, in je pomen boolovega izraza definiran kot v resitvi zgleda 1. Kaksen je potem pomen izraza: x or (y and not z) ?

Torej:

Mexp[x or (y and not z)] (<true, true, true>) = ?

Resitev:

Mexp[x or (y and not z)] (<true, true, true>) =
Mfact[x] (<true, true, true>) OR Mexp[(y and not z)] (<true, true, true>) =
Mvar[x] (<true, true, true>) OR Mexp[(y and not z)] (<true, true, true>) =
true OR Mexp[(y and not z)] (<true, true, true>) =
true OR Mfact[(y and not z)] (<true, true, true>) =
true OR Mexp[y and not z] (<true, true, true>) =
true OR (Mfact[y](<true, true, true>) AND Mexp[not z](<true, true, true>)) =
true OR (Mvar[y](<true, true, true>) AND Mexp[not z](<true, true, true>)) =
true OR (true AND Mfact[not z](<true, true, true>)) =
true OR (true AND (NOT Mfact[z](<true, true, true>))) =
true OR (true AND (NOT Mvar[z](<true, true, true>))) =
true OR (true AND (NOT true)) =
true OR (true AND false) =
true OR false =
true

Zgled 3:

Gornjo gramatiko(zgled 1) za boolove izraze razširimo s prireditvenim in sestavljenim stavkom, tako da je sintaktično pravi program:

```
program
  x := true ;
  y := false ;
  z := false ;
  x := x and y ;
  y := x or ( true and (not z) )
end
```

Ustrezno definiraj sintakso(v BNF notaciji) ter denotacijsko semantiko programa !

1. Sintaktična domena(v BNF notaciji):

```
<prog> ::=
  program <statements> end
<statements> ::=
  <lvar> := <exp> ; <statements> |
  <lvar> := <exp>
// <lvar> ima sint. enak pomen kot <var>, vendar drugačen semantični pomen !
<lvar> ::=
  x | y | z

// <exp> isto kot v Zgledu 1
<exp> ::=
  <fact> and <exp> | <fact> or <exp> |
  <fact>
<fact> ::=
  true | false | <var>
  not <fact> | ( <exp> )
<var> ::=
  x | y | z
```

2. Opis stanja in semantičnih funkcij:

```
State ≡ {true, false} x {true, false} x {true, false}
// stanje opisujejo vrednosti sprem. x, y in z
Mprog: prog -> (State -> State)
Mstatements: statements -> (State -> State)
Mlvar: lvar -> {1, 2, 3}
// <lvar> preslika ime spremenljivke v njen index v stanju
Mexp: exp -> (State -> { true, false })
// izraz preslika trenutno stanje sprem. x, y, in z v vrednost izraza true ali false
Mfact: fact -> (State -> { true, false })
Mvar: var -> (State -> { true, false })
```

3. Definicija semanticnih funkcij:

$M_{prog} [p:prog] (s:State) \equiv$
program <statements> end $\Rightarrow M_{statements}[p.statements](s)$

$M_{statements} [sts:statements] (<s1, s2, s3>:State) \equiv$
 <lvar> := <exp> ; <statements> \Rightarrow
 CASE $M_{lvar}[sts.lvar]$ OF
 1 $\Rightarrow M_{statements}[sts.statements](\langle M_{exp}[sts.exp](s), s2, s3 \rangle)$
 2 $\Rightarrow M_{statements}[sts.statements](\langle s1, M_{exp}[sts.exp](s), s3 \rangle)$
 3 $\Rightarrow M_{statements}[sts.statements](\langle s1, s2, M_{exp}[sts.exp](s) \rangle)$
 END
 <lvar> := <exp> \Rightarrow
 CASE $M_{lvar}[sts.lvar]$ OF
 1 $\Rightarrow \langle M_{exp}[sts.exp](s), s2, s3 \rangle$
 2 $\Rightarrow \langle s1, M_{exp}[sts.exp](s), s3 \rangle$
 3 $\Rightarrow \langle s1, s2, M_{exp}[sts.exp](s) \rangle$
 END

$M_{lvar} [lv:lvar] \equiv$
 x \Rightarrow 1 |
 y \Rightarrow 2 |
 z \Rightarrow 3

$M_{exp} [e:exp] (s:State) \equiv$
 <fact> and <exp> $\Rightarrow M_{fact}[e.fact](s) \text{ AND } M_{exp}[e.exp](s) |$
 <fact> or <exp> $\Rightarrow M_{fact}[e.fact](s) \text{ OR } M_{exp}[e.exp](s) |$
 <fact> $\Rightarrow M_{fact}[e.fact](s)$

$M_{fact} [f:fact] (s:State) \equiv$
 true \Rightarrow true |
 false \Rightarrow false |
 <var> $\Rightarrow M_{var}[f.var](s) |$
 not <fact> $\Rightarrow \text{NOT } M_{fact}[f.fact](s) |$
 (<exp>) $\Rightarrow M_{exp}[f.exp](s)$

$M_{var} [v:var] (<xVal, yVal, zVal>:State) \equiv$
 x \Rightarrow xVal |
 y \Rightarrow yVal |
 z \Rightarrow zVal