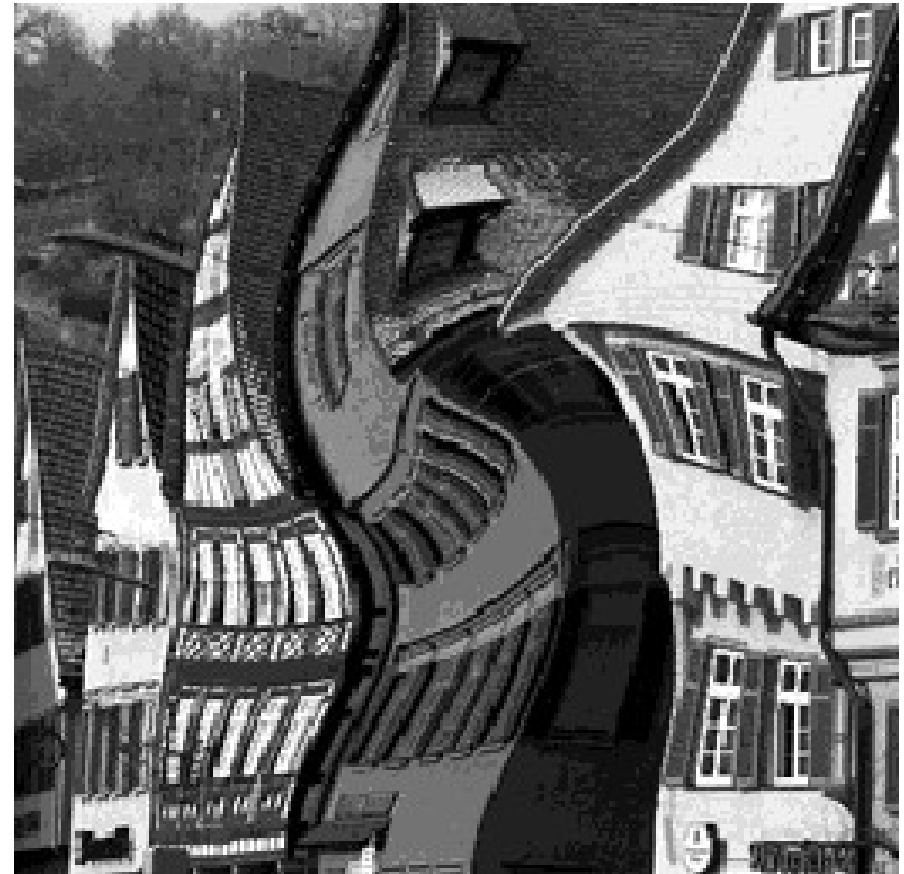
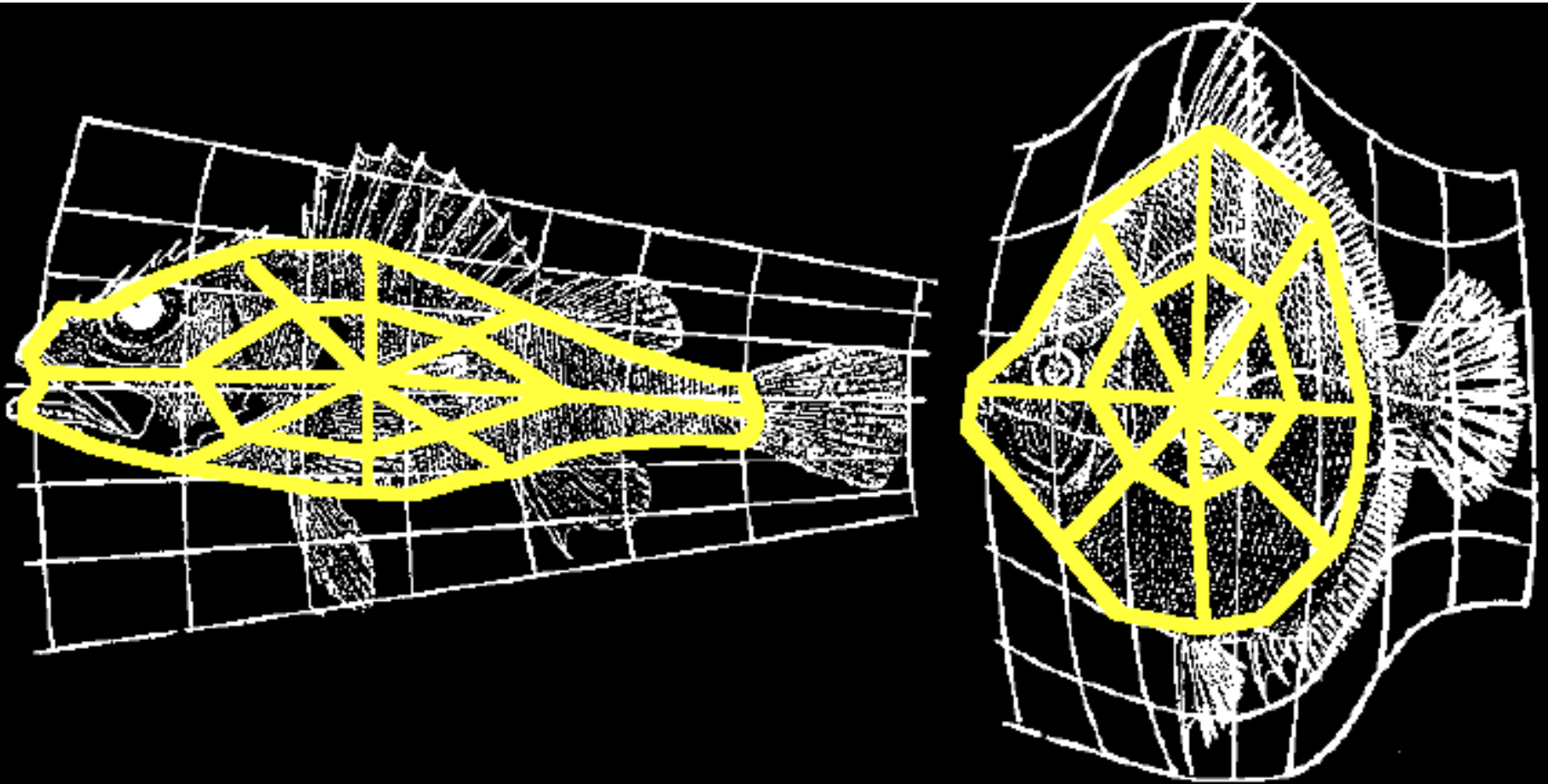


Krivljenje slike - warping



Princip 2D krivljenja

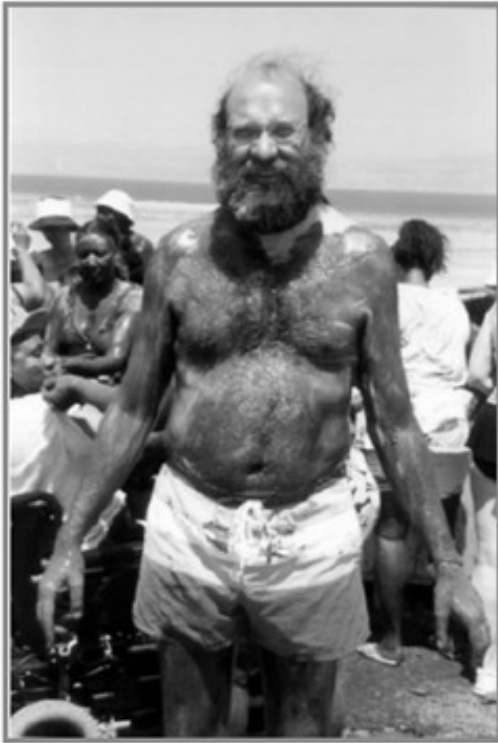


Demo

Krivljenje (Warping)

- A warp is a 2-D geometric transformation and generates a distorted image when it is applied to an image.
- **Warping** an image means : apply a given deformation to it.
- Two ways to warp an image:-
 - Forward mapping.
 - Reverse mapping.

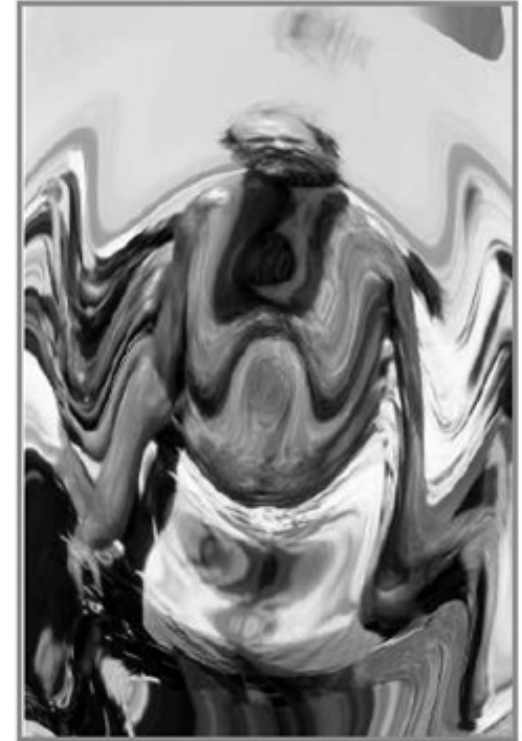
Krivljenje (Warping)



Source image



warp

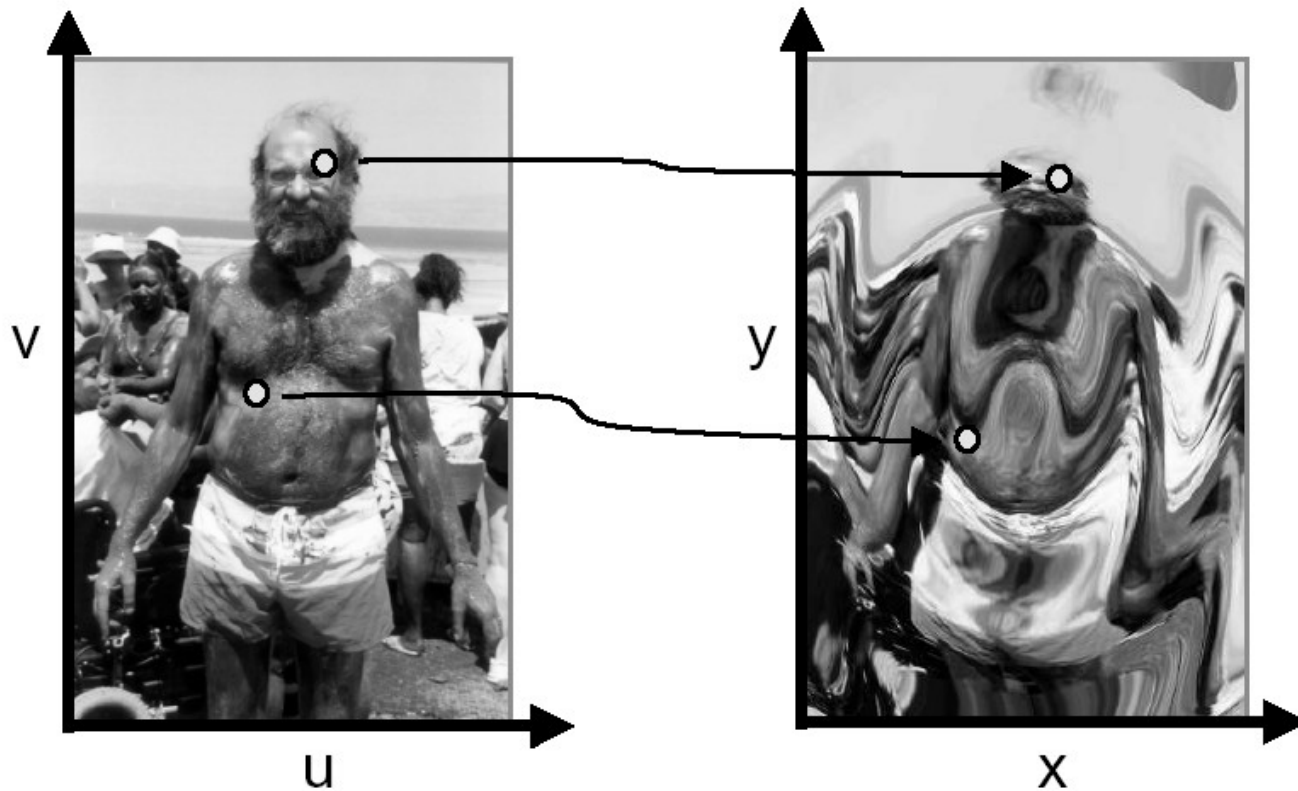


Destination image

- Mapping
 - Forward
 - Reverse
- Resampling
 - Point sampling
 - Triangle filter
 - Gaussian filter

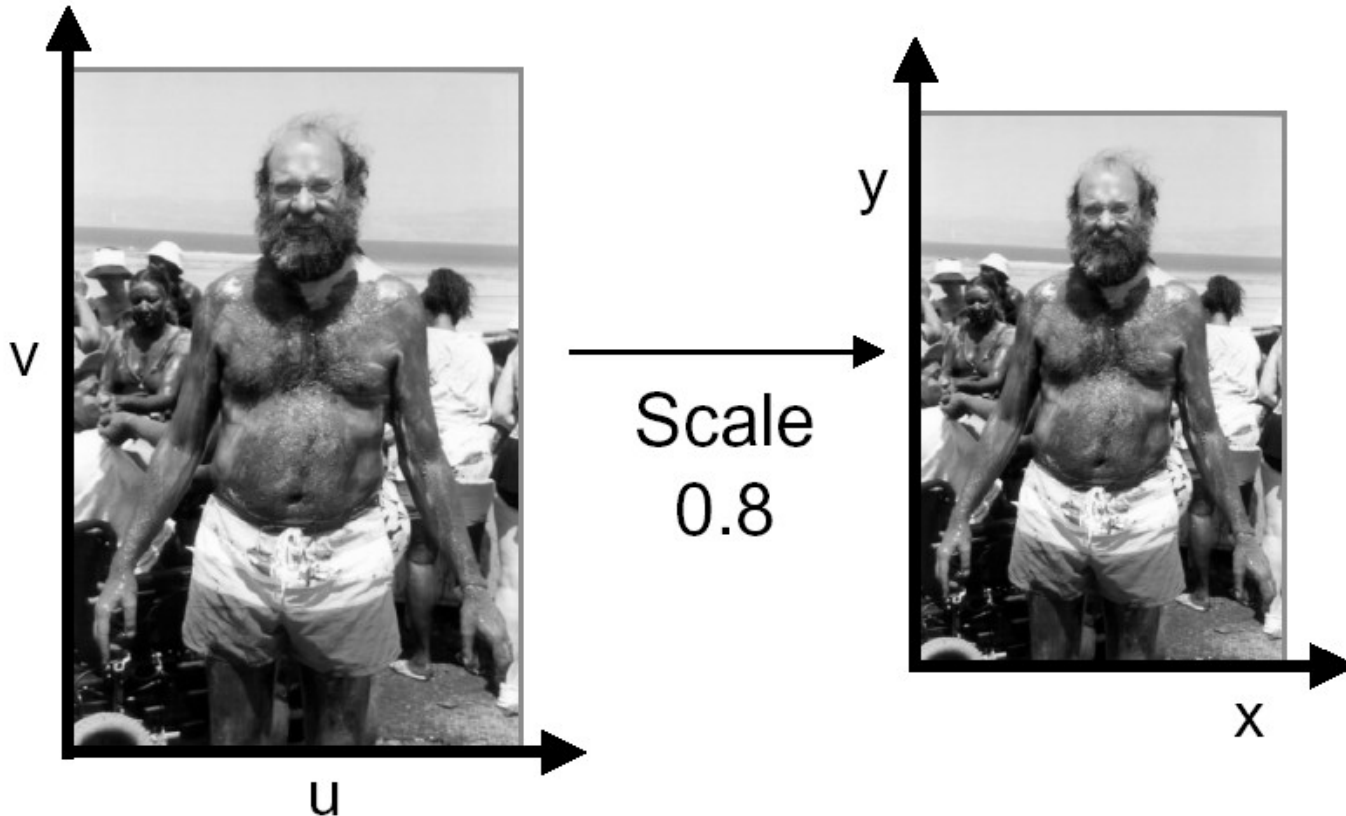
Preslikava (mapping)

- Define transformation
 - Describe the destination (x,y) for every location (u,v) in the source (or vice-versa, if invertible)



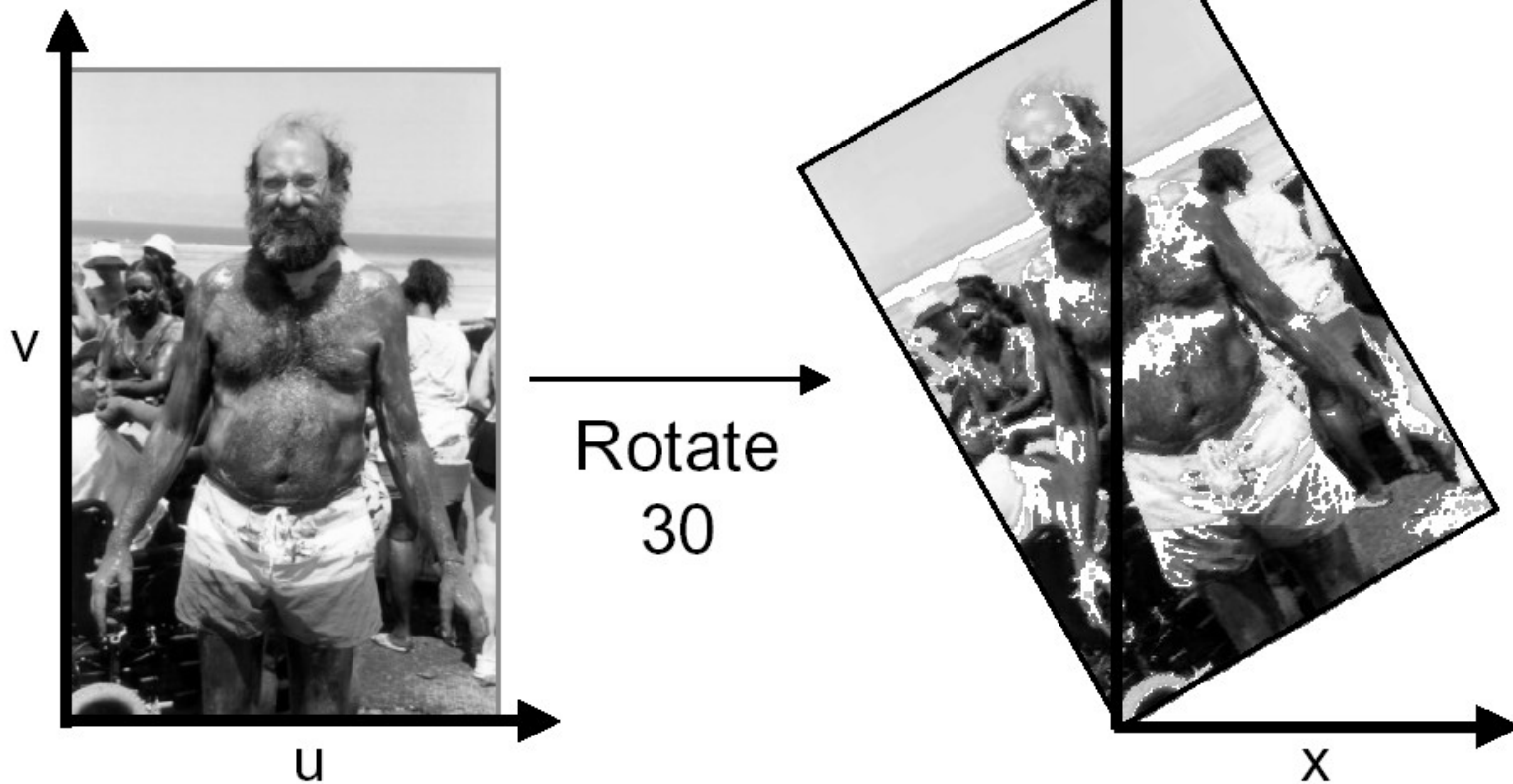
Primer preslikave

- Scale by *factor*:
 - $x = factor * u$
 - $y = factor * v$



Primer preslikave

- Rotate by Θ degrees:
 - $x = u \cos \Theta - v \sin \Theta$
 - $y = u \sin \Theta + v \cos \Theta$

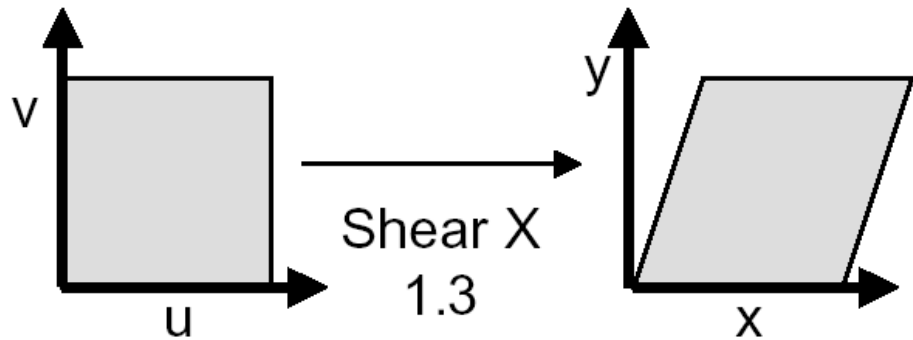


Primer preslikave

- Shear in X by *factor*:

- $x = u + \textit{factor} * v$

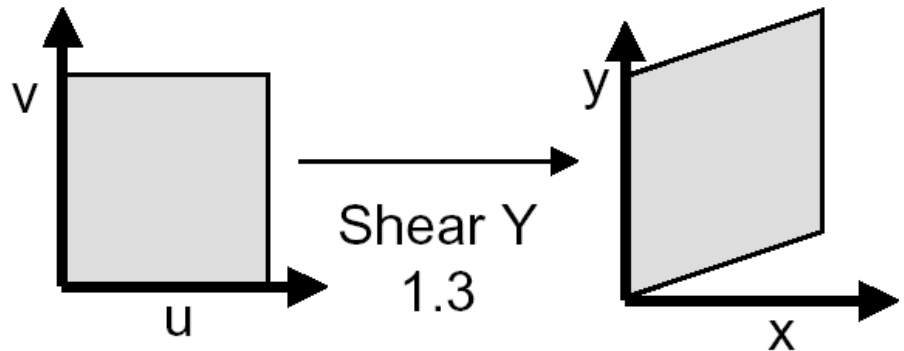
- $y = v$



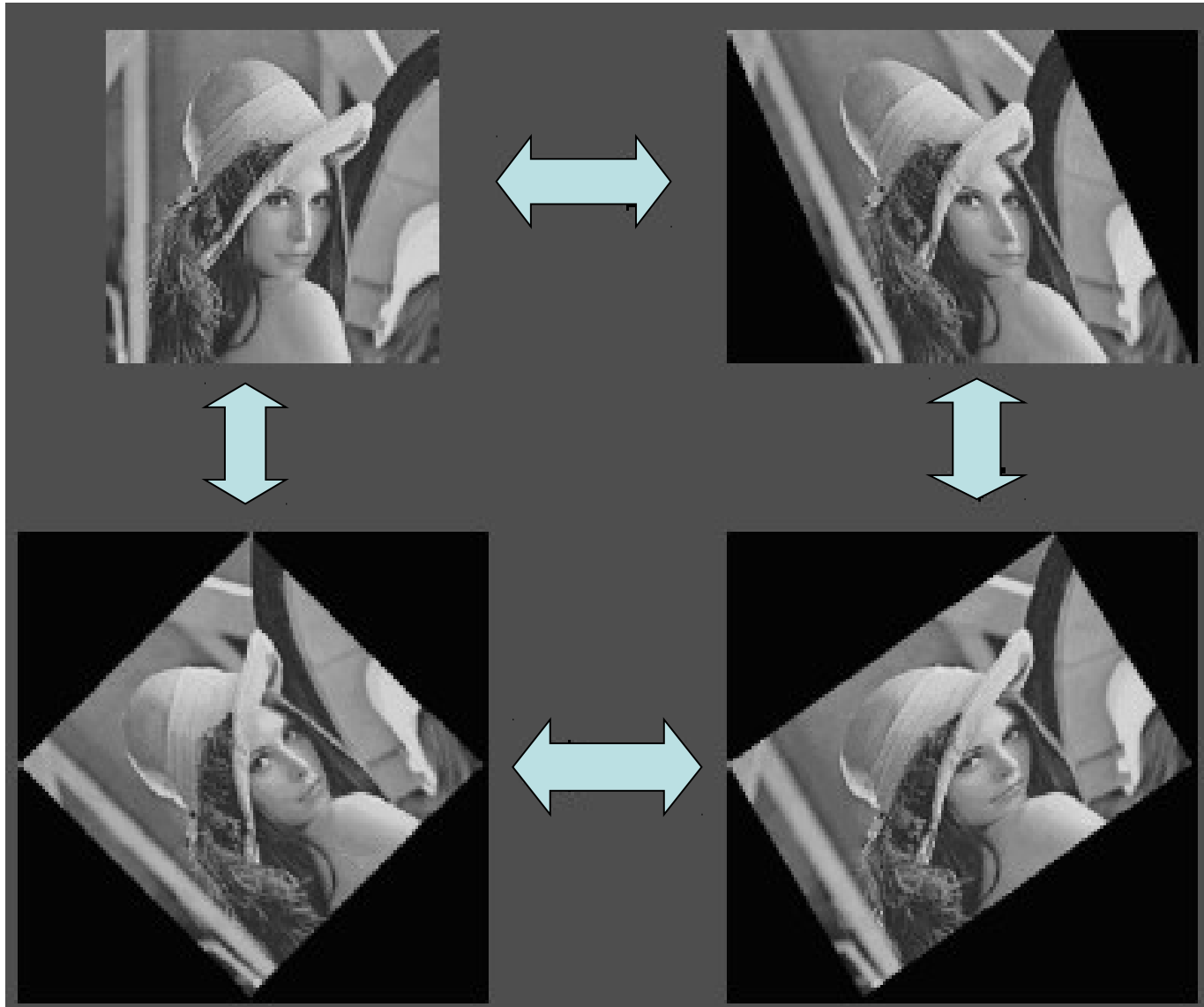
- Shear in Y by *factor*:

- $x = u$

- $y = v + \textit{factor} * u$

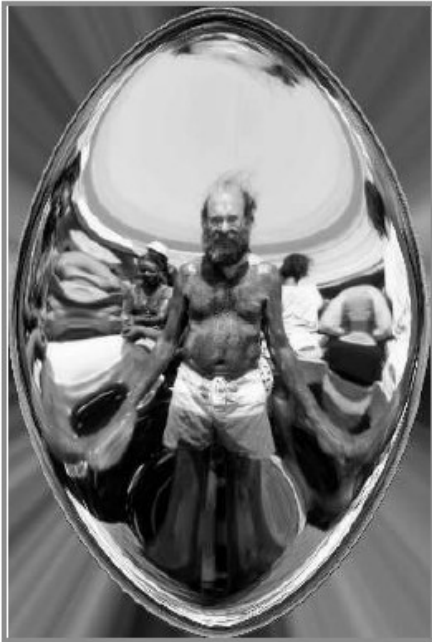


Primer krivljenja



Other Mappings

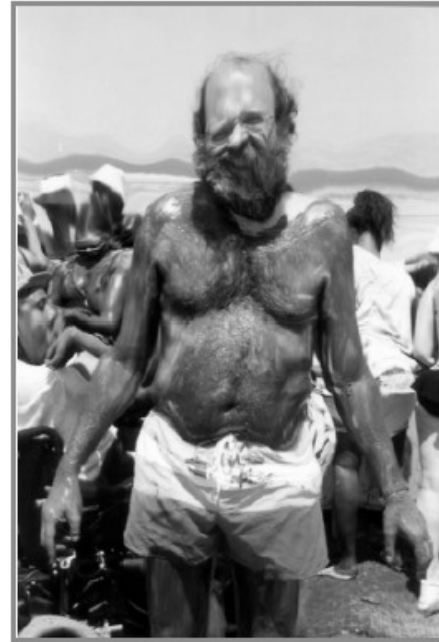
- Any function of u and v :
 - $x = f_x(u,v)$
 - $y = f_y(u,v)$



Fish-eye



“Swirl”

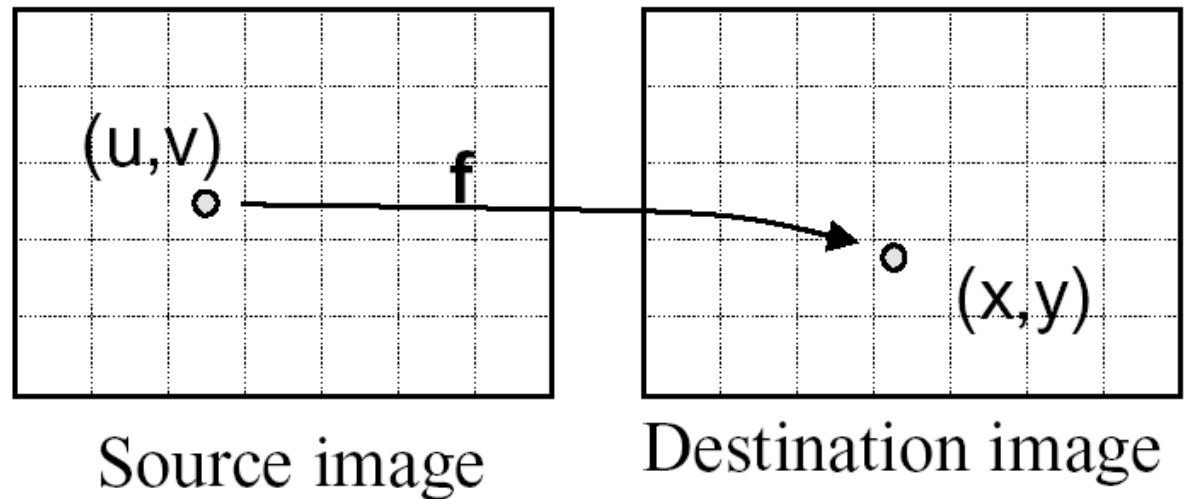


“Rain”

Image Warping Implementation I

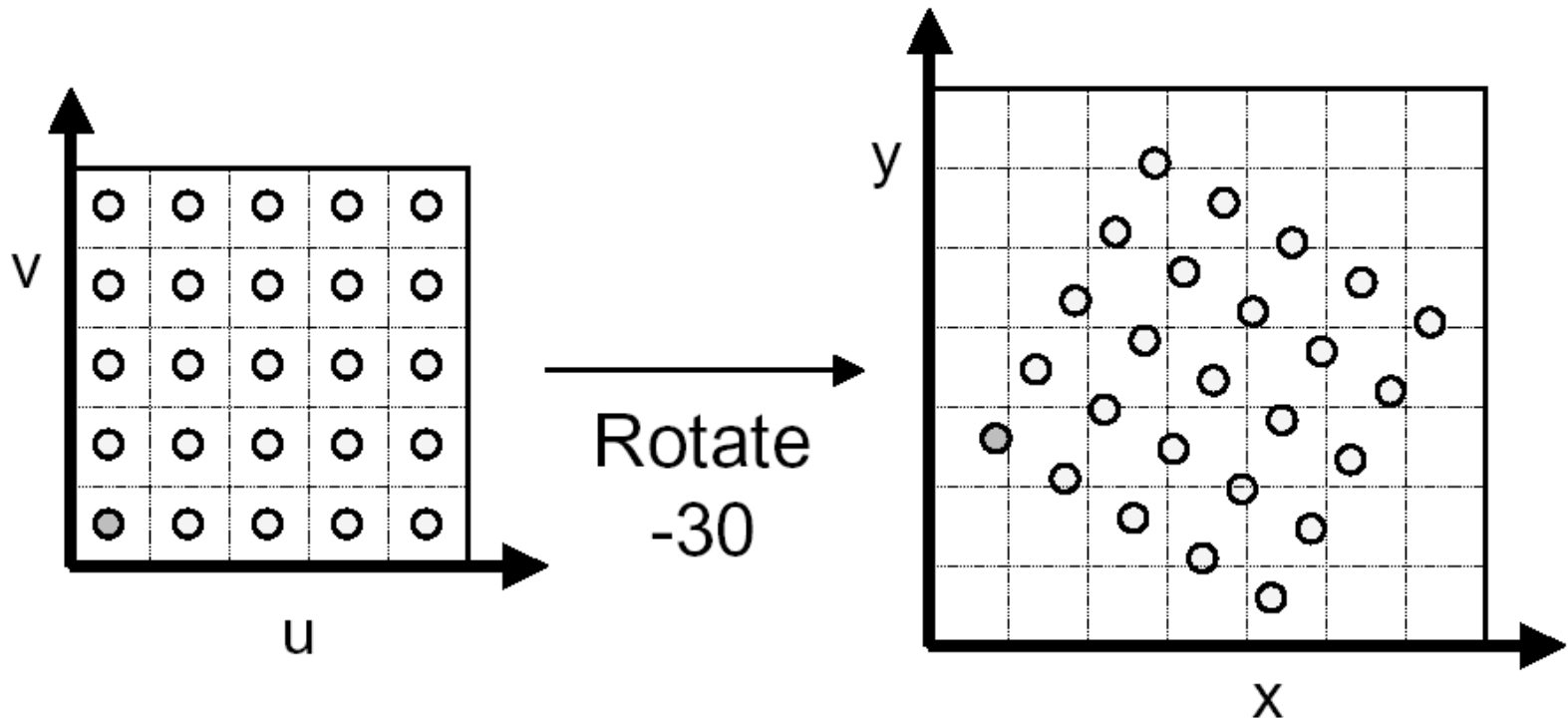
- Forward mapping:

```
for (int u = 0; u < umax; u++) {  
    for (int v = 0; v < vmax; v++) {  
        float x = fx(u,v);  
        float y = fy(u,v);  
        dst(x,y) = src(u,v);  
    }  
}
```



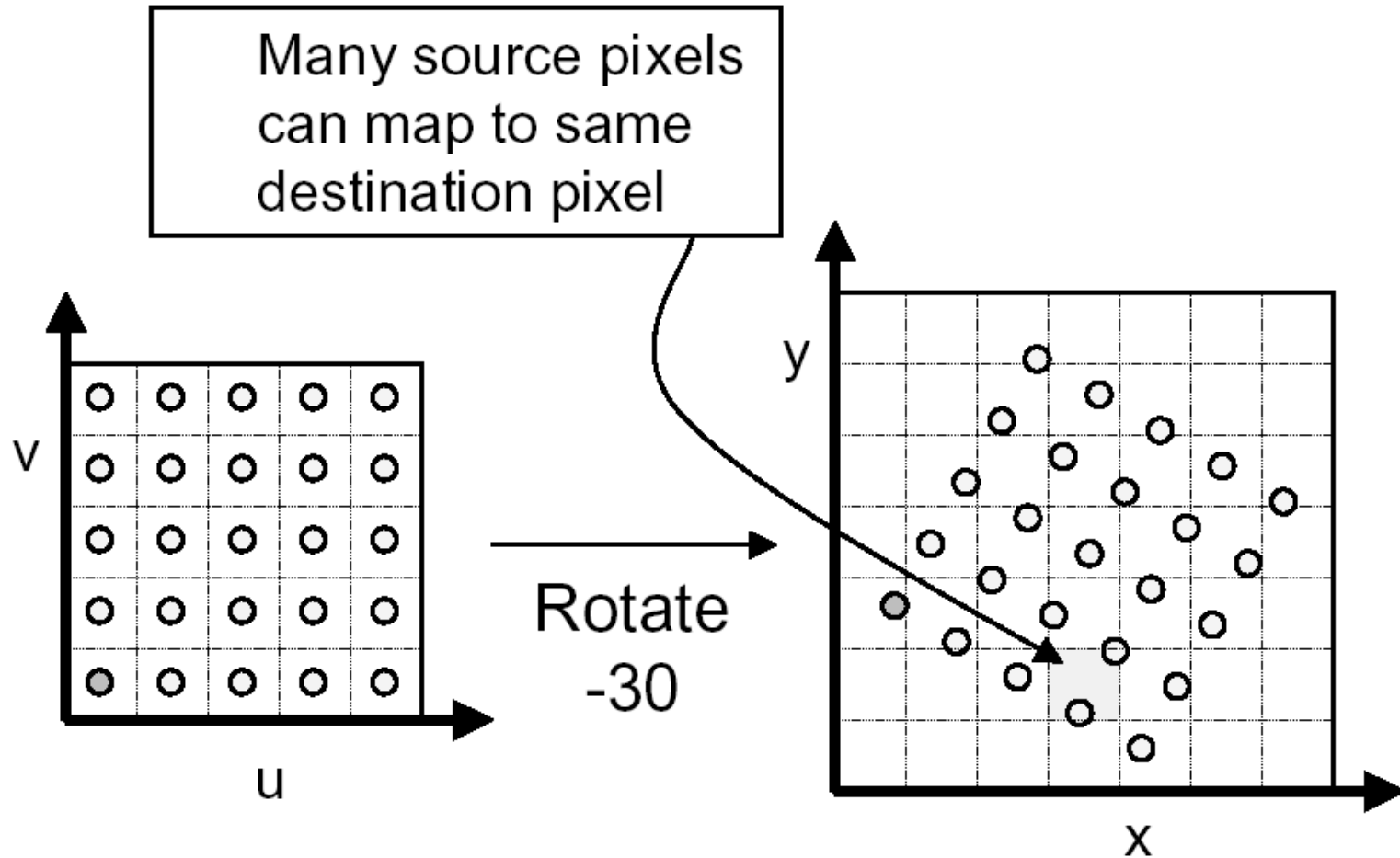
Forward Mapping

- Iterate over source image



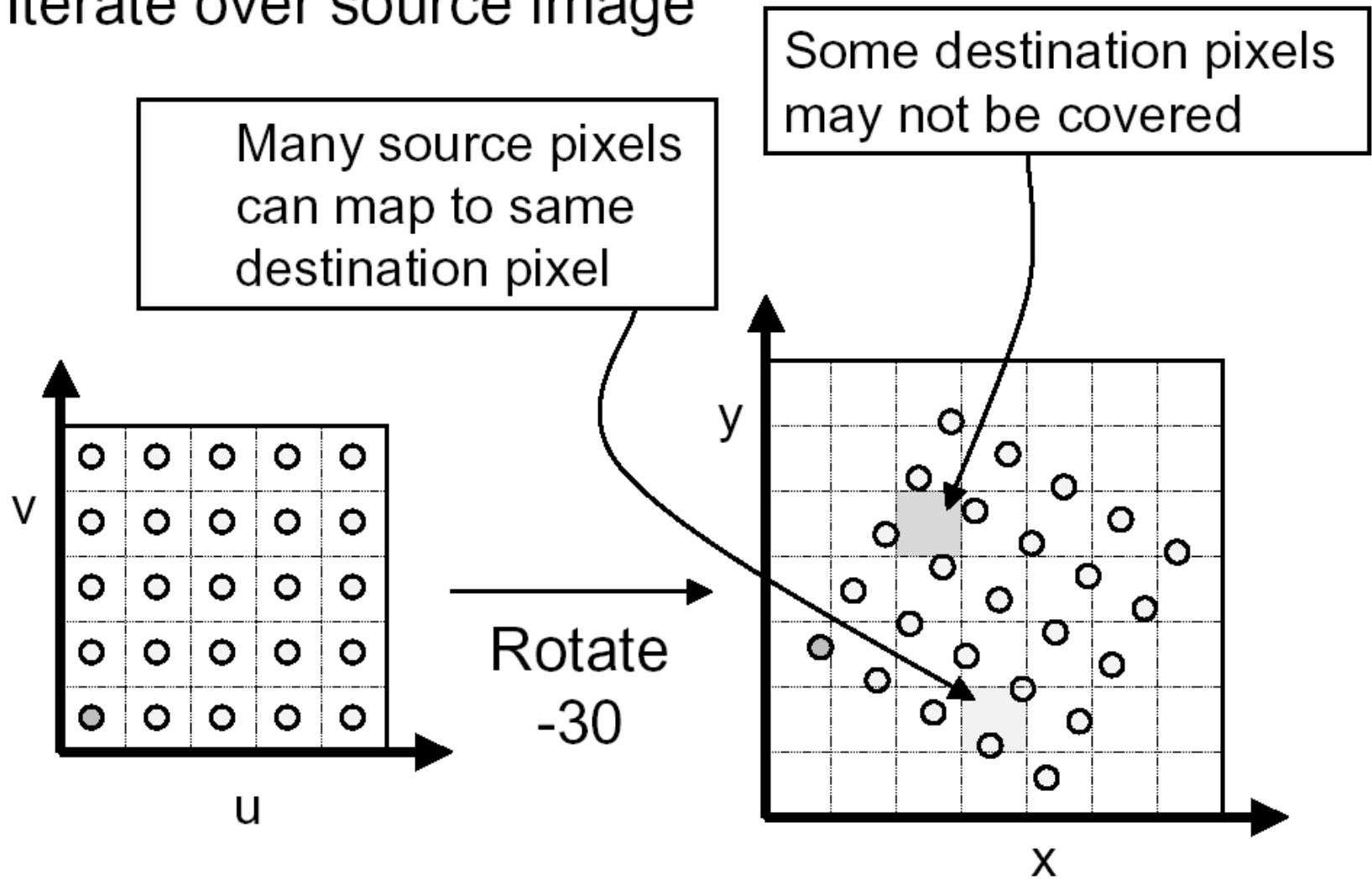
Forward Mapping

- Iterate over source image



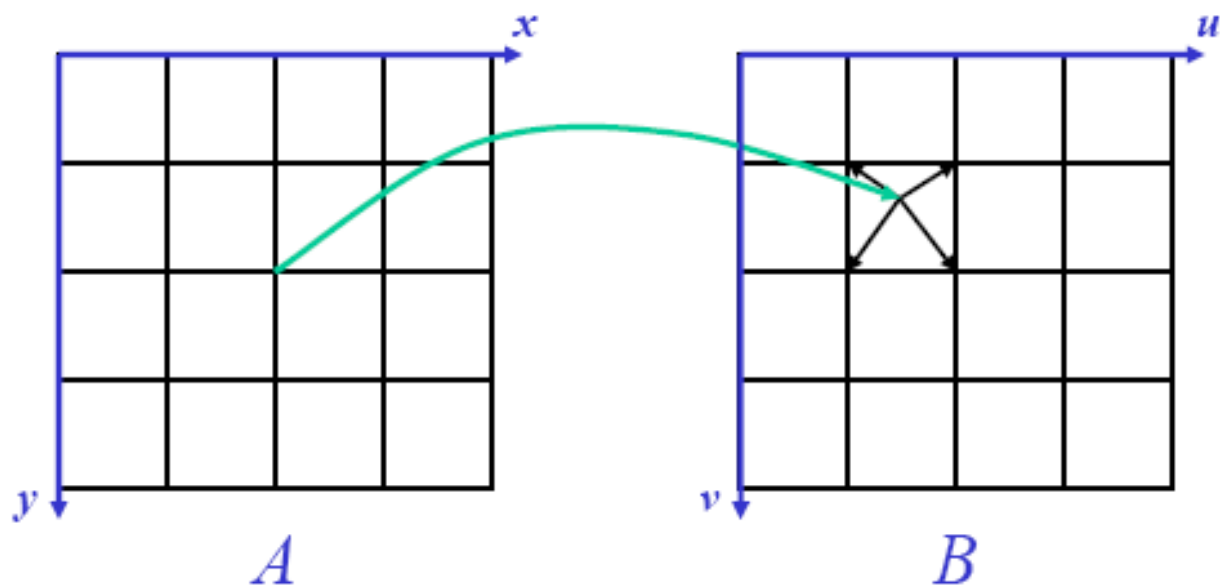
Forward Mapping

- Iterate over source image



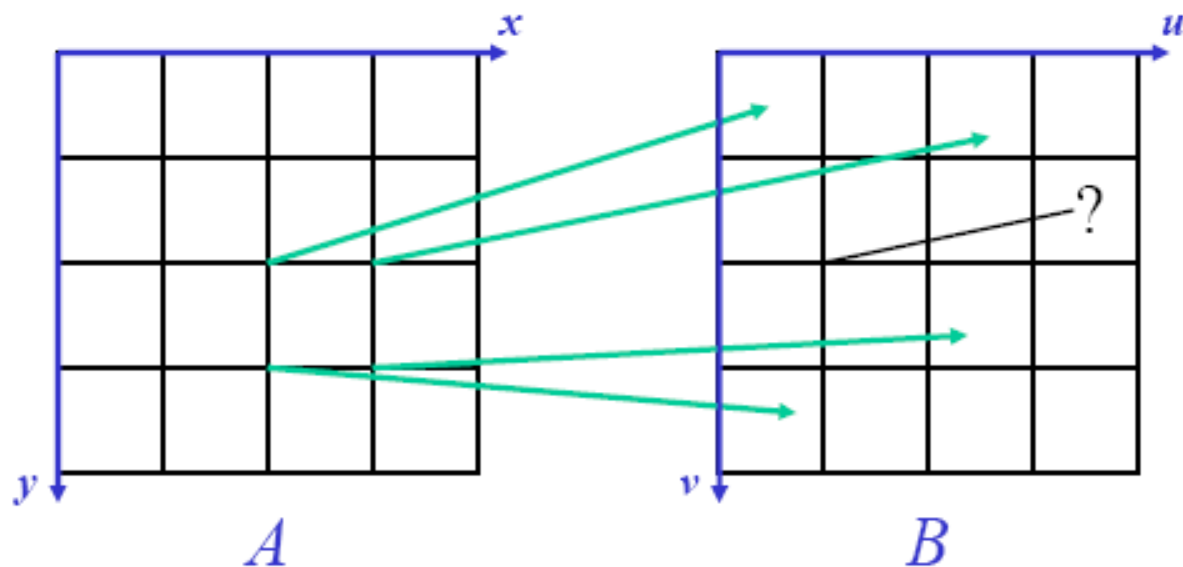
Forward Mapping: Problems

- Doesn't always map *to* pixel locations
- Solution: spread out effect of each pixel, e.g. by bilinear interpolation



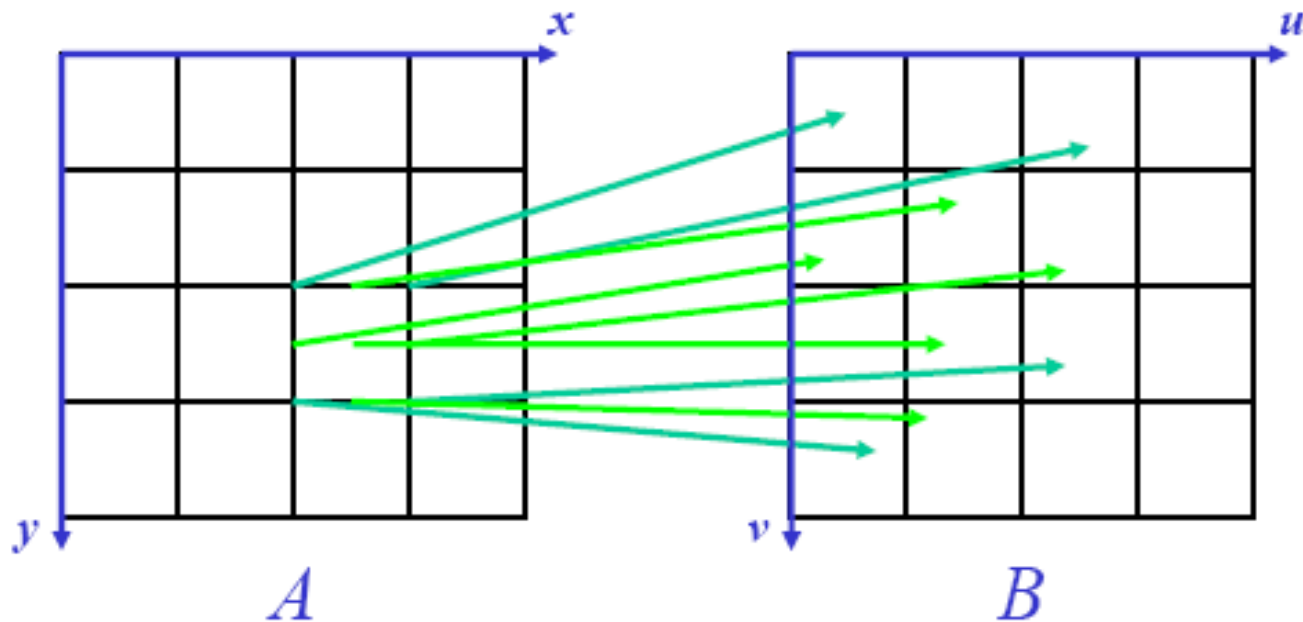
Forward Mapping: Problems

- May produce holes in the output



Forward Mapping: Problems

- May produce holes in the output
- Solution: sample source image (A) more often
 - Still can leave holes



Backward Mapping

Let $x(u, v)$ and $y(u, v)$ be an inverse mapping from location (x, y) to (u, v) :

$$B[u, v] = A[x(u, v), y(u, v)]$$

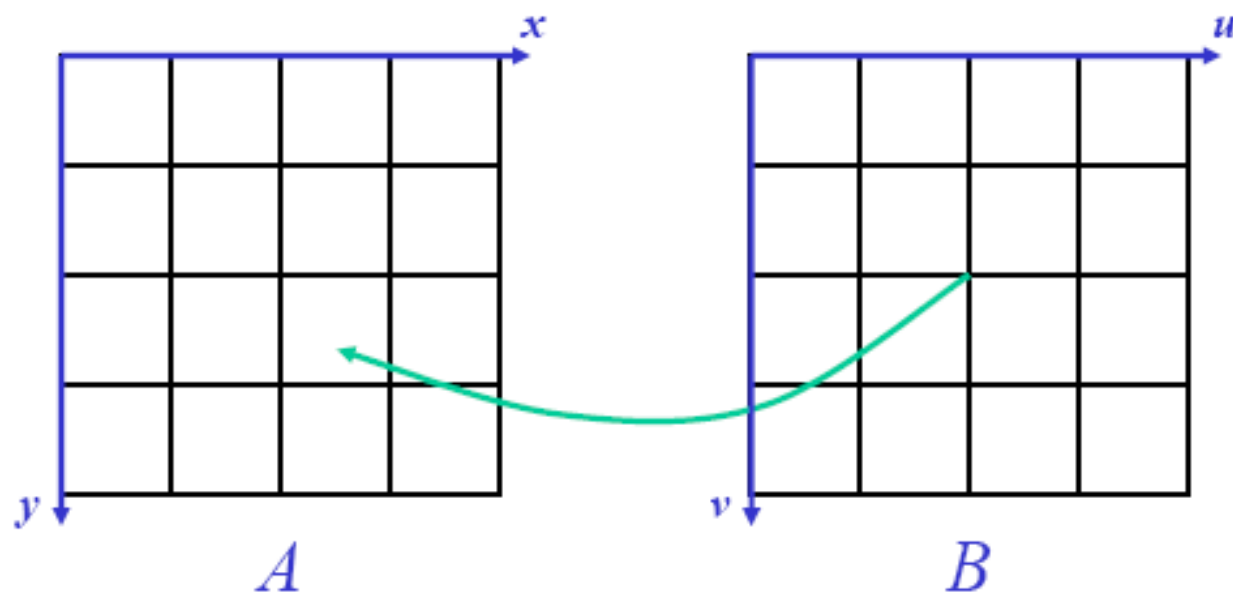
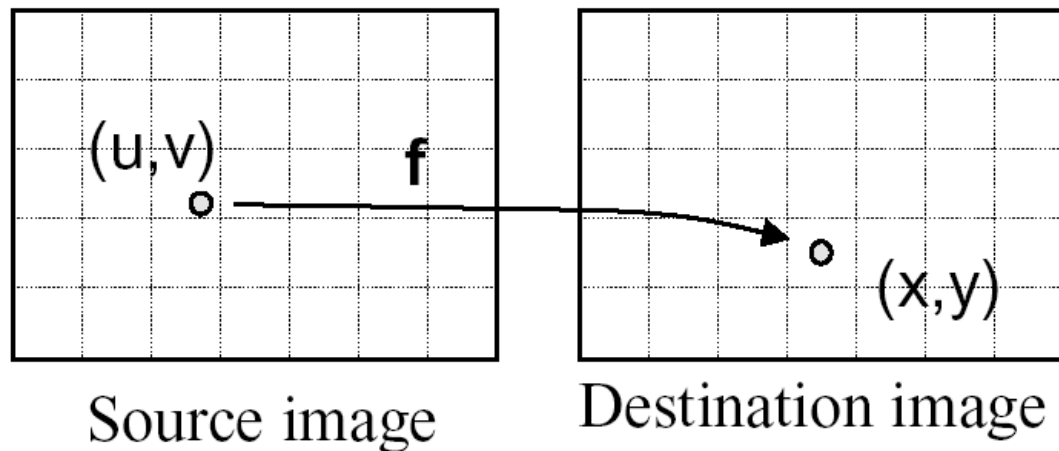


Image Warping Implementation II

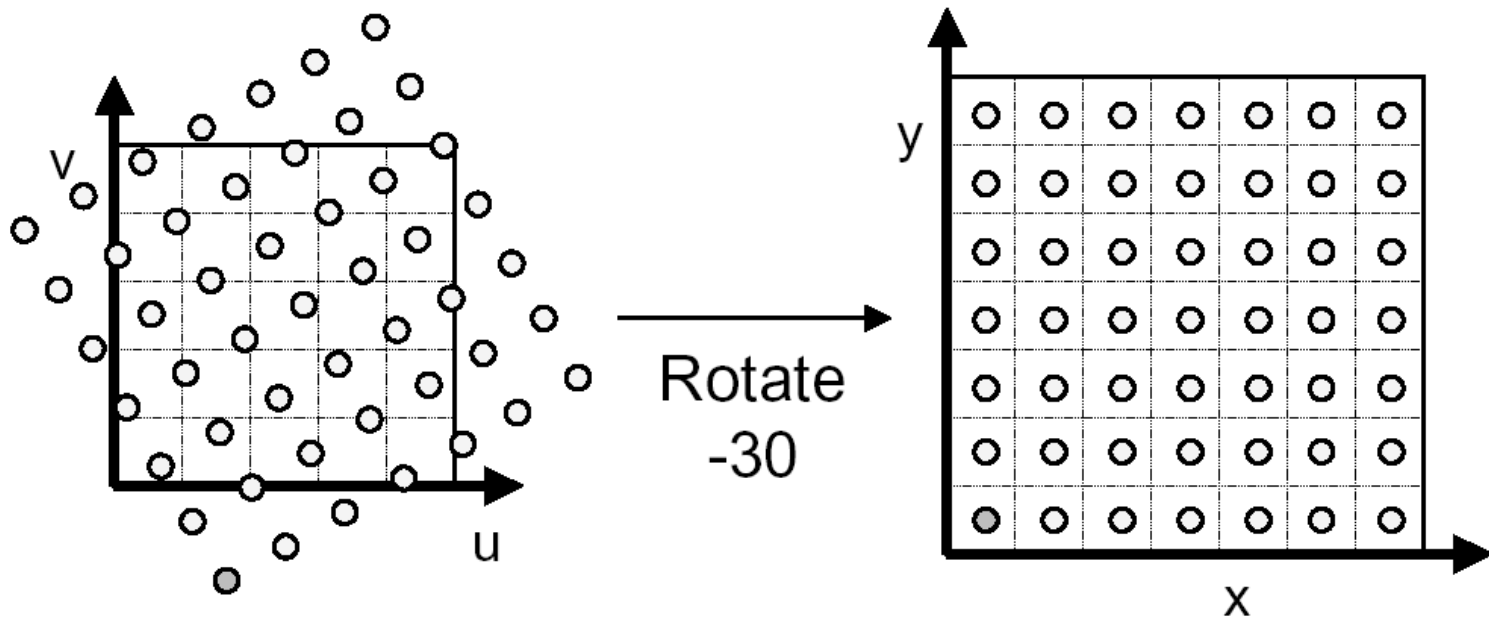
- Reverse mapping:

```
for (int x = 0; x < xmax; x++) {  
  for (int y = 0; y < ymax; y++) {  
    float u =  $f_x^{-1}(x, y)$ ;  
    float v =  $f_y^{-1}(x, y)$ ;  
    dst(x, y) = src(u, v);  
  }  
}
```



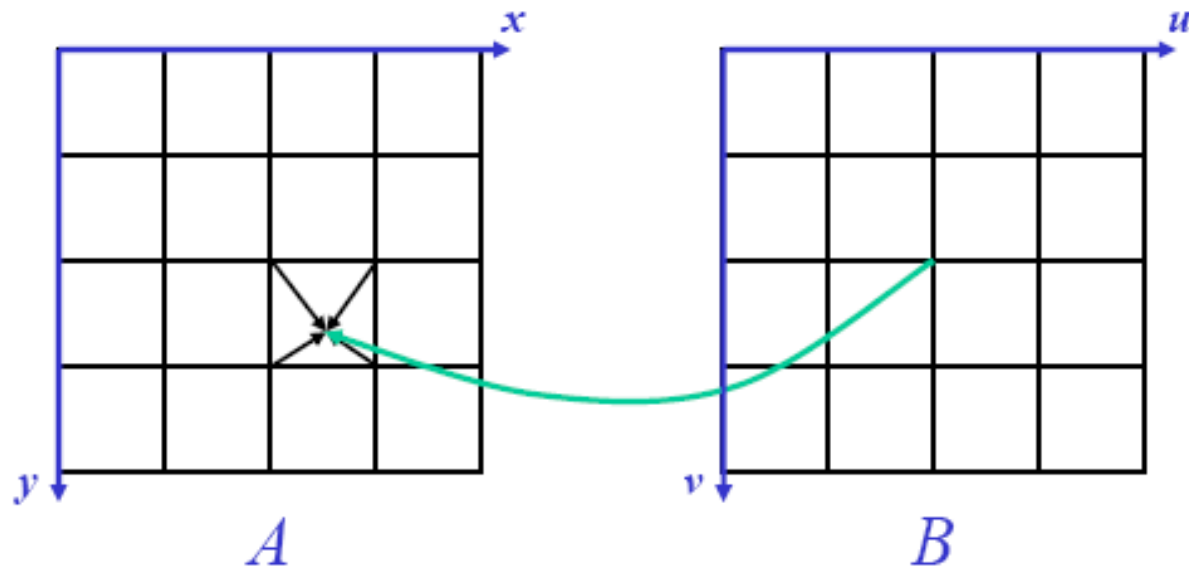
Reverse Mapping

- Iterate over destination image
 - Must resample source
 - May oversample, but much simpler!



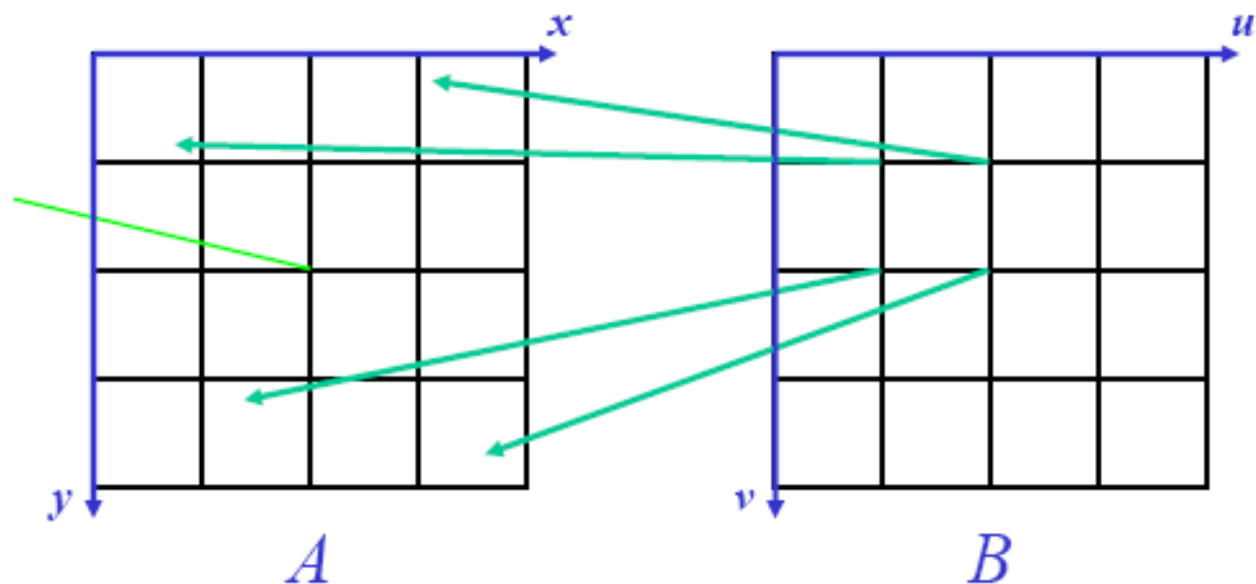
Backward Mapping: Problems

- Doesn't always map *from* a pixel
- Solution: Interpolate between pixels



Backward Mapping: Problems

- May produce holes in the input
- Solution: reduce input image (by averaging pixels) and sample reduced/averaged image \rightarrow MIP-maps

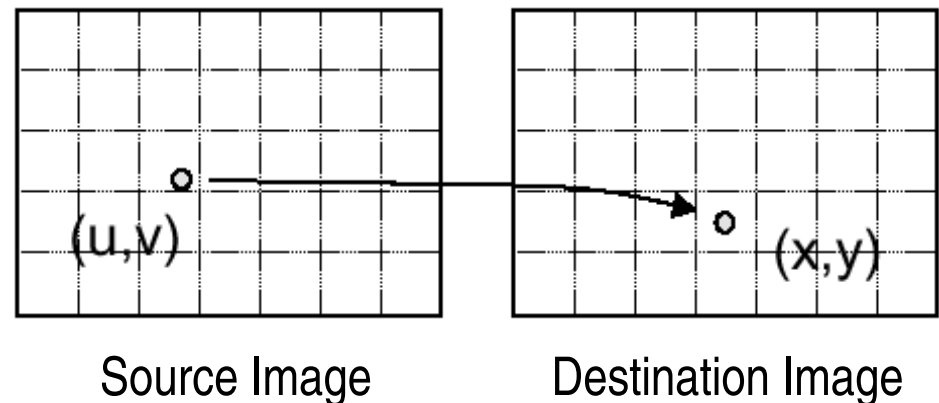


Forward and Reverse Mapping

- Forward → Some pixels in the destination might not get painted, and would have to be interpolated.
- Reverse → Every pixel in the destination image gets set to something appropriate.

Resampling

- Evaluate source image at arbitrary (u, v)
 - (u, v) does not usually have integer coordinates
- Some kinds of resampling
 - Point resampling
 - Triangle filter
 - Gaussian filter

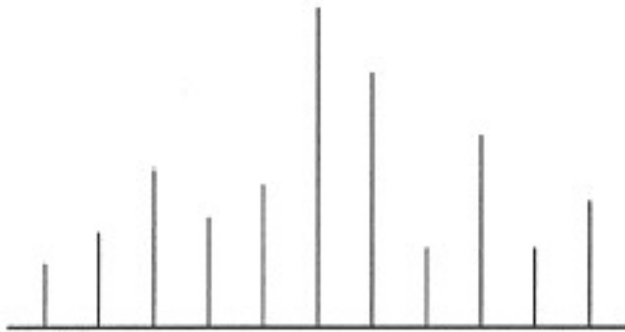


Point Sampling

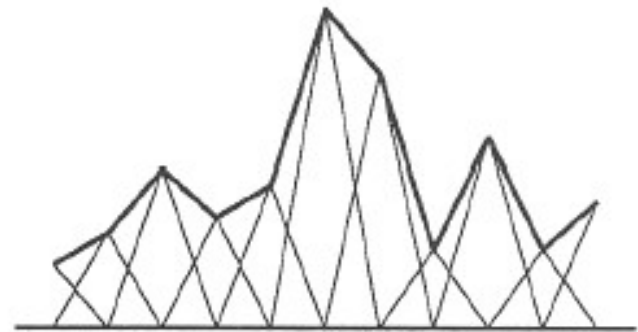
- Take value at closest pixel
int iu = trunc(u + 0.5);
int iv = trunc(v + 0.5);
dst(x, y) = src(iu, iv);
- Simple, but causes aliasing

Triangle Filter

- Convolve with triangle filter



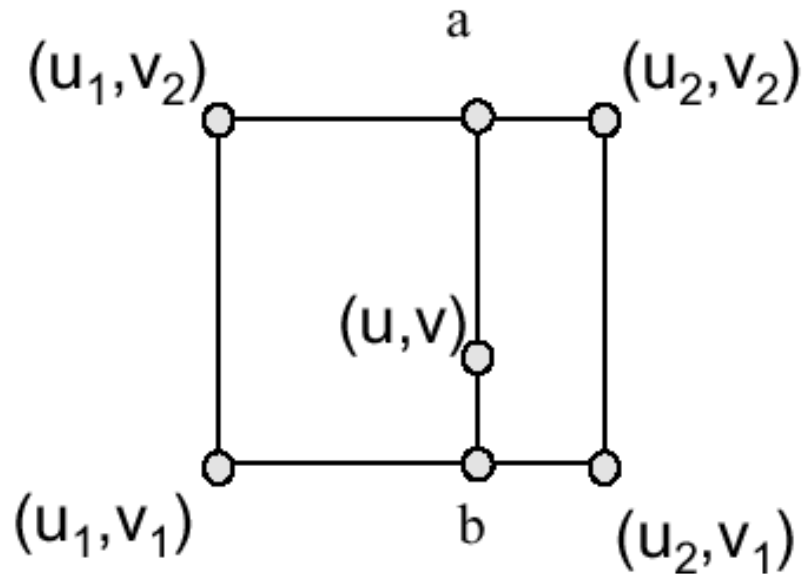
Input



Output

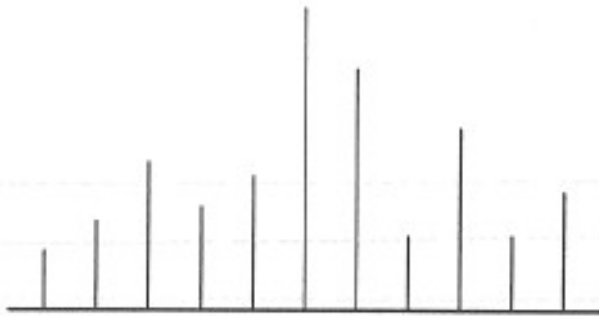
Triangle Filter

- Bilinearly interpolate four closest pixels
 - a = linear interpolation of $\text{src}(u_1, v_2)$ and $\text{src}(u_2, v_2)$
 - b = linear interpolation of $\text{src}(u_1, v_1)$ and $\text{src}(u_2, v_1)$
 - $\text{dst}(x, y)$ = linear interpolation of 'a' and 'b'

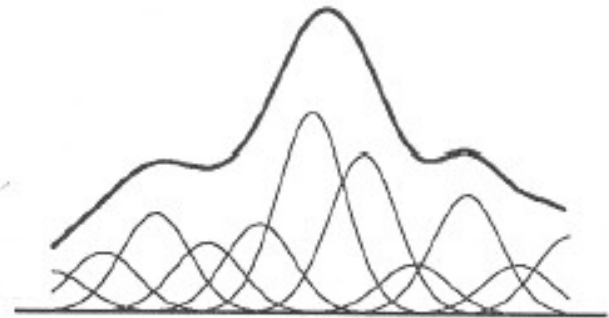


Gaussian Filter

- Convolve with Gaussian filter



Input



Output

Width of Gaussian kernel affects bluriness

Filtering Method Comparison

- Trade-offs
 - Aliasing versus blurring
 - Computation speed

Image Warping Implementation

- Reverse mapping:

```
for (int x = 0; x < xmax; x++) {  
    for (int y = 0; y < ymax; y++) {  
        float u =  $f_x^{-1}(x,y)$ ;  
        float v =  $f_y^{-1}(x,y)$ ;  
        dst(x,y) = resample_src(u,v,w);  
    }  
}
```

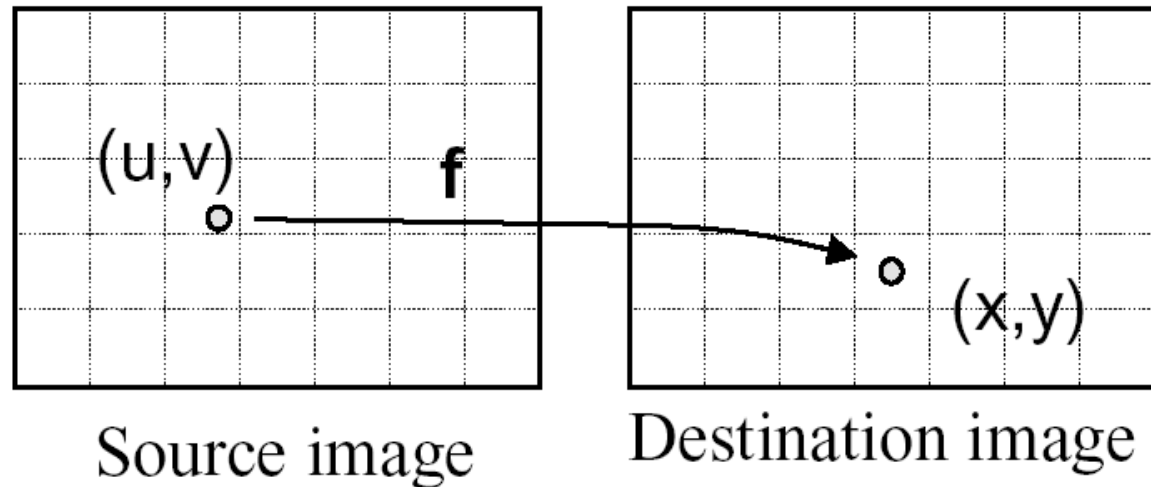
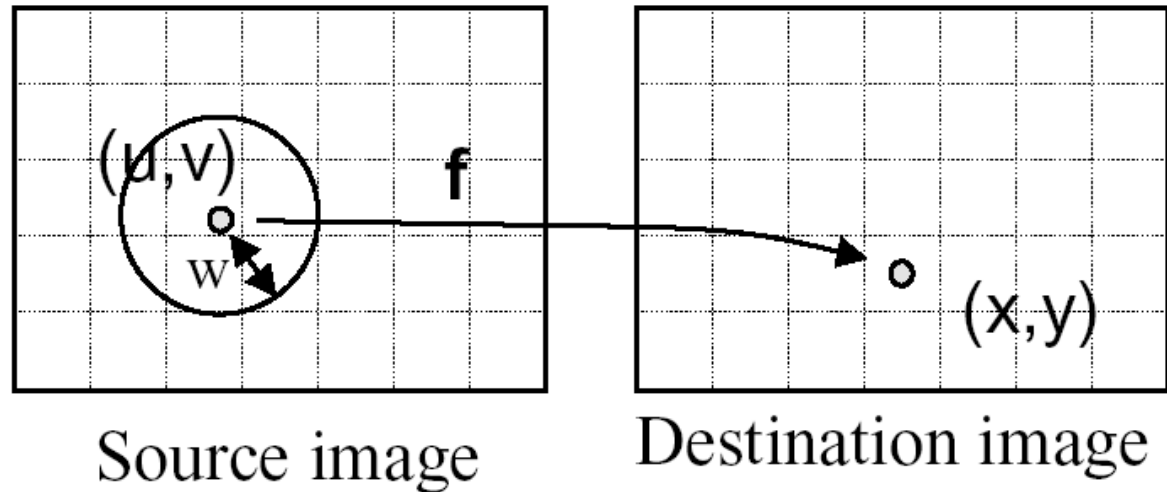


Image Warping Implementation

- Reverse mapping:

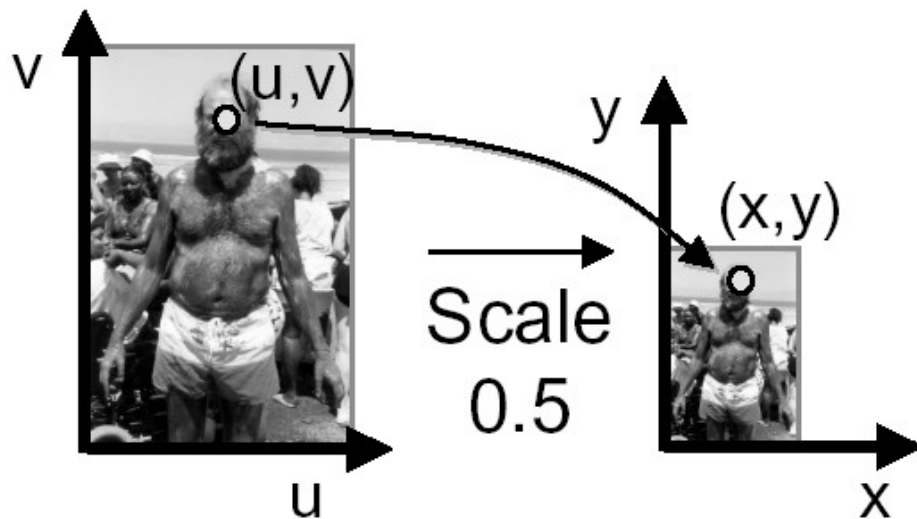
```
for (int x = 0; x < xmax; x++) {  
    for (int y = 0; y < ymax; y++) {  
        float u =  $f_x^{-1}(x, y)$ ;  
        float v =  $f_y^{-1}(x, y)$ ;  
        dst(x, y) = resample_src(u, v, w);  
    }  
}
```



Example: Scale

- Scale (src, dst, sx, sy):

```
float w ≅ max(1.0/sx, 1.0/sy);  
for (int x = 0; x < xmax; x++) {  
    for (int y = 0; y < ymax; y++) {  
        float u = x / sx;  
        float v = y / sy;  
        dst(x,y) = resample_src(u,v,w);  
    }  
}
```

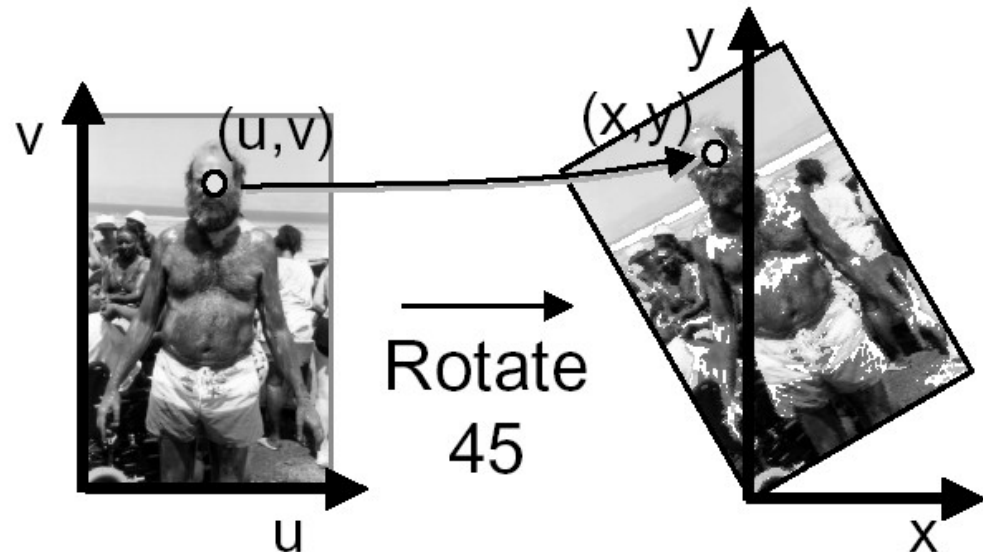


Example: Rotate

- Rotate (src, dst, theta):

```
for (int x = 0; x < xmax; x++) {  
  for (int y = 0; y < ymax; y++) {  
    float u = x*cos(-Θ) - y*sin(-Θ);  
    float v = x*sin(-Θ) + y*cos(-Θ);  
    dst(x,y) = resample_src(u,v,w);  
  }  
}
```

$$x = u\cos\Theta - v\sin\Theta$$
$$y = u\sin\Theta + v\cos\Theta$$



Example: Swirl

- Swirl (src, dst, theta):

```
for (int x = 0; x < xmax; x++) {  
    for (int y = 0; y < ymax; y++) {  
        float u = rot(dist(x, xcenter) * theta);  
        float v = rot(dist(y, ycenter) * theta);  
        dst(x, y) = resample_src(u, v, w);  
    }  
}
```

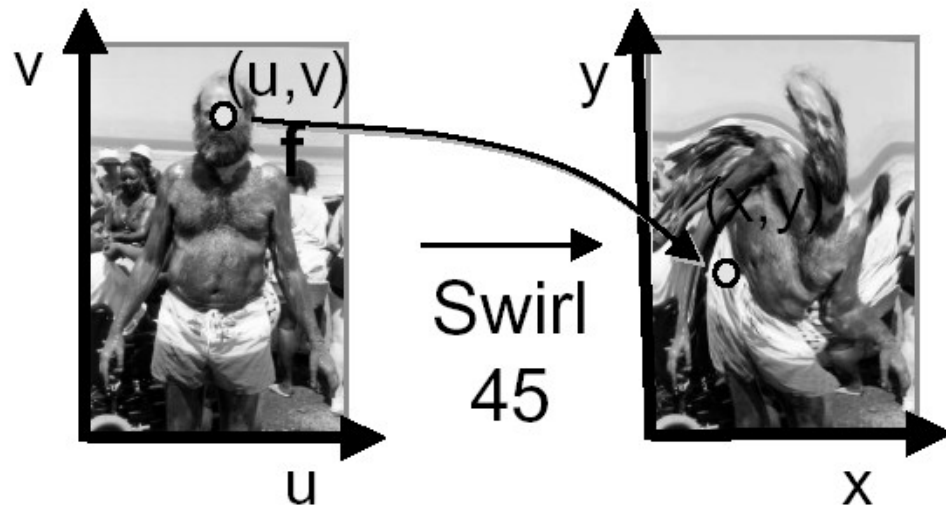


Image Warping: Summary

- Mapping
 - Forward
 - Reverse
- Resampling
 - Point sampling
 - Triangle filter
 - Gaussian filter

Reverse mapping
is simpler to implement

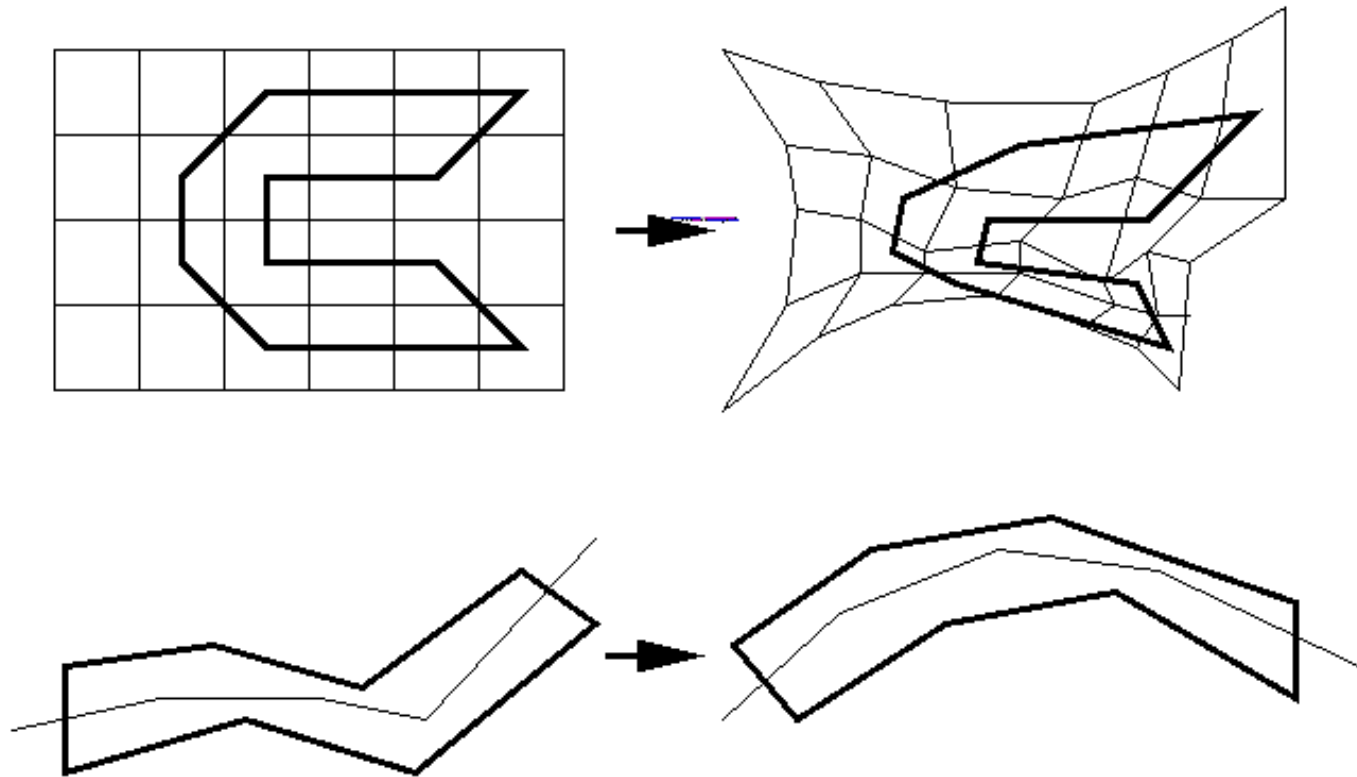
Different filters trade-off
speed and aliasing/blurring

Fun and creative warps
are easy to implement!

Forward and Reverse Mapping

- In either case, the problem is to determine the way in which the pixels in one image should be mapped to the pixels in the other image.
- So, we need to specify **how each pixel moves** between the two images.
- This could be done by specifying the mapping for a few important pixels.

Two Dimensional Object Warping

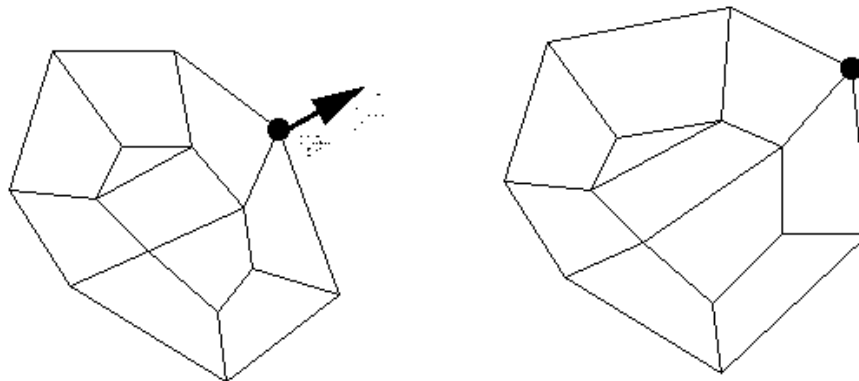


Two Dimensional Object Warping

- The shape modification can also be performed on a **vertex-basis** instead of on a space-basis.
- A displacement for a seed vertex can be specified by the user and this displacement can be propagated to nearby vertices.
- The **displacement** can be attenuated as a **function of the distance** that the vertex to be displaced is away from the seed vertex.

Two Dimensional Object Warping

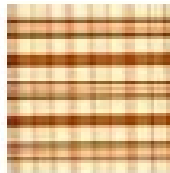
- The **distance function** can be chosen to trade-off quality of results and computational complexity.
 - Minimum number of edges connecting the vertex to be displaced from the seed vertex.
 - Minimum distance traveled over the surface of the object to get from the vertex to be displaced to the seed vertex.
 - Power functions to control the amount of attenuation.
 - The user could select the maximum distance at which the displacement would have an affect.



Texture Mapping

The process of “pasting” a 2D image on a 3D object.

When viewed after projection, this is just a 2D warp of the original texture with hidden surface elimination.



texture map



texture mapped object

Texture mapping

