3D rezanje 3D Clipping
view frustrum

clipped

## 3D Projections and Clipping

- Projections (Concluded)
- Parallel projection: cuboid view volume
- Perspective projection: truncated pyramidal view volume (frustum)
- Problem: how to clip?
- Clipping
- Given: coordinates for primitives (line segments, polygons, circles, ellipses, etc.)
- Determine: visible components of primitives (e.g., line segments)
- Methods
- Solving simultaneous equations (quick rejection: testing endpoints)
- Solving parametric equations
- Objectives: efficiency (e.g., fewer floating point operations)
- Clipping in 3D
- Some 2D algorithms extendible to 3D
- Specification (and implementation) of view volumes needed


## Paralelni kuboid in View volume



## 3D Clipping

- For orthographic projection, view volume is a box.
- For perspective projection, view volume is a frustrum.



## 3D obrezovanje poligonov

It is sufficient to clip each polygon against the view pyramid.


Far
Plane

## Canonical View Volume



- Can use Cohen-Sutherland algorithm.
- Now 6-bit outcode.
- Trivial acceptance where both endpoint outcodes are all zero.
- Perform logical AND, reject if non-zero.
- Find intersect with a bounding plane and add the two new lines to the line queue.
- Line-primitive algorithm.
- Sutherland-Hodgman extends easily to 3D.
- Call ‘CLIP' procedure 6 times rather than 4
- Polygon-primitive algorithm.



## Sutherland-Hodgman Algorithm

## Four cases of polygon clipping :



## Clipping and Homogeneous Coordinates

- Efficient to transform frustrum into perspective canonical view volume - unit slope planes.
- Even better to transform to parallel canonical view volume
- Clipping must be done in homogeneous coordinates.
- Points can appear with -ve W and cannot be clipped properly in 3D.


## Why Clip Against Near and Far?



## Clipping Against Pyramid Sides

Let $l, r, b, t$ be the points where the sides of the view pyramid intersect the view plane. Let $d$. be the distance from the origin to the view point. Then

$$
\begin{array}{ll}
\text { slope of the left plane: } & s_{L}=-1 / 2(r-l) / d \\
\text { slope of the right plane: } & s_{R}=1 / 2(r-l) / d \\
\text { slope of the bottom plane: } & s_{B}=-1 / 2(t-b) / d \\
\text { slope of the top plane: } & s_{T}=1 / 2(t-b) / d
\end{array}
$$



## Equations of the Sides of the View Pyramid

$$
\begin{array}{ll}
L: & x=l+s_{L} z \\
R: & x=r+s_{R} z \\
B: & y=b+s_{B} z \\
T: & y=t+s_{T} z \\
N: & z=n \\
F: & z=f
\end{array}
$$

A line from $\left(x_{1}, y_{1}, z_{1}\right)$ to $\left(x_{2}, y_{2}, z_{2}\right)$ intersects the top plane at $u$ value

$$
u_{T}=\frac{y_{1}-t-s_{T} z_{1}}{y_{1}-y_{2}+s_{T}\left(z_{2}-z_{1}\right)}
$$

so we compute the $(x, y, z)$ point of intersection as

$$
x=x_{1}+u_{T}\left(x_{2}-x_{1}\right) \quad y=y_{1}+u_{T}\left(y_{2}-y_{1}\right) \quad z=z_{1}+u_{T}\left(z_{2}-z_{1}\right)
$$

## 3D Clipping Pipeline

The code is exactly analogous to the 2D pipeline with two more clippers: $N$ (near) and $F$ (far).


## 3D Clipping Pipeline (2)

Front View


## 3D Clipping Pipeline (3)

Top View


## 3D Clipping Pipeline (4)

First iteration:

| $O$ |  | $O$ |  | $O$ |  | $O$ |  | $O$ |  | $O$ |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $P_{1}$ | $L$ | $P_{1}$ | $R$ | $P_{1}$ | $B$ | $P_{1}$ | $T$ | $a$ | $N$ | $a$ | $F$ | $a$ |
| $P_{2}$ | $L$ | $P_{2}$ | $R$ | $P_{2}$ | $B$ | $P_{2}$ | $T$ |  |  |  |  |  |
| $P_{3}$ | $L$ | $P_{3}$ | $R$ | $b$ | $B$ | $b$ | $T$ | $c$ | $N$ | $c$ | $F$ | $d$ |
|  |  |  |  |  |  |  |  | $b$ | $N$ | $b$ | $F$ |  |

Second Iteration:

| $P_{3}$ |  | $P_{3}$ |  | $b$ |  | $b$ |  | $b$ |  | $b$ |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $P_{1}$ | $L$ | $P_{1}$ | $R$ | $e$ | $B$ | $e$ | $T$ | $f$ | $N$ | $f$ | $F$ | $g$ |
|  |  |  |  |  |  |  |  |  |  |  |  | $f$ |
|  |  |  |  | $P_{1}$ | $B$ | $P_{1}$ | $T$ |  |  |  |  |  |
| $P_{2}$ | $L$ | $P_{2}$ | $R$ | $P_{2}$ | $B$ | $P_{2}$ | $T$ |  |  |  |  |  |
| $P_{3}$ | $L$ | $P_{3}$ | $R$ | $b$ | $B$ | $b$ | $T$ | $c$ | $N$ | $c$ | $F$ | $h$ |
|  |  |  |  |  |  |  |  | $b$ | $N$ | $b$ | $F$ |  |

