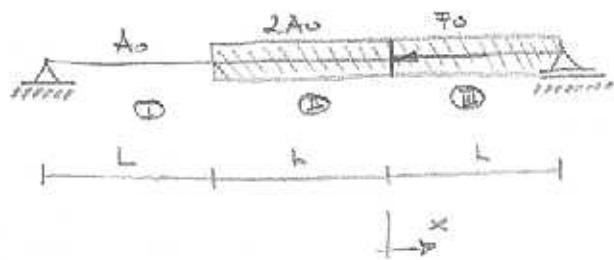


Izračun naslednji sistem



V vseli pogoj je  $\frac{d^2w}{dx^2} = 0$ , ker  
ni prisotne obrumenitve

- Robni pogoji so:

$$u_1(x=0) = 0 \quad \checkmark$$

$$N_3(x=L) = 0 \quad \checkmark$$

$$u_2'(x=0) = 0$$

- Pogoji konistentnega preluda

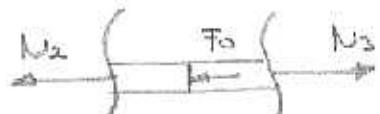
$$u_1(x=-L) = u_2(x=-L) \quad \checkmark$$

$$u_2(x=0) = u_3(x=0) \quad \checkmark$$

$$N_1(x=-L) = N_2(x=-L) \quad \checkmark$$

$$\Rightarrow EA_0 u_1'(x=-L) = 2EA_0 u_2'(x=-L)$$

$\Rightarrow$  Velja po se:



$$N_2 + F_0 = N_3$$

$$N_2(x=0) + T_0 = N_3(x=0)$$

$\Rightarrow$  Se pri x = 0 velja

$$2EA_0 u_2'(x=0) + T_0 = 2EA_0 u_2'(x=0)$$

Zapišemo:

$$u_1(x) = \tilde{C}_0 + \tilde{C}_1 x = (x+2L) C_0 = C_0 + C_{1L} = (x+2L) C_0$$

$$u_2(x) = u_1(x) + (C_2 + C_3 x) = u_1(x) + C_1 x$$

$$u_3(x) = u_2(x) + u_3(x) + (C_4 + C_5 x) = u_2(x) + C_2 x$$

$$u_1'(x) = C_0$$

$$u_2'(x) = C_0 + C_3$$

$$u_3'(x) = C_0 + C_0 + C_3 + C_5$$

~~$$k \frac{d^2w}{dx^2} = 0 \text{ in der}$$~~

$$\bullet \quad u_2(x=L) = 2EA_0, \quad u_2'(x=L) = 0$$

$$\hookrightarrow u_2'(x=L) = 0 = [2C_0 + C_2 + C_3] = 0$$

$$\bullet \quad u_2(x=0) = u_2(x=0)$$

$$[2L C_0 + C_2] = 2L C_0 + [2L C_0 + C_2] + C_4$$

$$C_4 = -2L C_0$$

$$\bullet \quad M_1(x=-L) = M_2(x=-L)$$

$$EA_0 u_1'(x=-L) = 2EA_0 u_2'(x=-L)$$

$$C_0 = 2 [C_0 + C_2]$$

$$C_0 = -2C_2 \rightarrow C_2 = -\frac{1}{2}C_0$$

$$\bullet \quad u_1(x=-L) = u_2(x=-L)$$

$$L C_0 = L C_0 + [C_2 - L C_3]$$

$$C_2 = L C_3 \rightarrow C_2 = -\frac{1}{2}C_0$$

$$\begin{aligned} x C_0 &= 2L C_0 & x C_2 \\ C_0 &= 2L C_0 & C_2 = -\frac{1}{2}C_0 \end{aligned}$$

$$\hookrightarrow 2C_0 - \frac{1}{2}C_0 + C_3 = 0$$

$$C_3 = -\frac{3}{2}C_0$$

$$\bullet \quad 2EA_0 \cdot [C_0 - \frac{1}{2}C_0] + F_0 = 2EA_0 [2C_0 - \frac{1}{2}C_0 - \frac{3}{2}C_0]$$

$$EA_0 C_0 = -F_0$$

$$C_0 = -\frac{F_0}{EA_0}$$

Sledi:

$$C_0 = -\frac{F_0}{EA_0}$$

$$u_1(x) = (x+2L) \left[ -\frac{F_0}{EA_0} \right]$$

$$C_2 = \frac{F_0}{2EA_0}$$

$$u_2(x) = (x+2L) \left[ -\frac{F_0}{EA_0} \right] + \left[ \frac{F_0}{2EA_0} + \frac{F_0}{2EA_0} x \right] =$$

$$C_3 = \frac{F_0}{2EA_0}$$

$$u_2(x) = (x+2L) \left[ -\frac{F_0}{EA_0} \right] + \left( \frac{F_0}{2EA_0} \right) \cdot \left[ L + x \right] =$$

$$C_4 = \frac{2L F_0}{EA_0}$$

$$u_2(x) = \frac{F_0}{EA_0} \left[ -x - 2L + \frac{1}{2}L + \frac{1}{2}x \right] =$$

$$C_5 = \frac{3F_0}{2EA_0}$$

$$u_2(x) = \frac{F_0}{EA_0} \left[ x + 3L \right]$$

$$u_2(x) = (x+2L) \left[ -\frac{F_0}{EA_0} \right] - \frac{F_0}{2EA_0} \left[ x+3L \right] + \left[ \frac{2L F_0}{EA_0} + \frac{3F_0}{2EA_0} x \right]$$

$$u_3(x) = \frac{F_0}{EA_0} \left[ -x - 2L - \frac{1}{2}x - \frac{3}{2}L + 2L + \frac{3}{2}x \right]$$

Heniseidovo koordinatų funkcijos:

$$w_1(x) = (x + 2L) \left[ -\frac{\bar{T}_0}{EA_0} \right]$$

$$w_2(x) = (x + 2L) \left[ -\frac{\bar{T}_0}{EA_0} \right] + \left[ \frac{\bar{T}_0 L}{2EA_0} + \frac{\bar{T}_0 x}{2EA_0} \right]$$

$$w_3(x) = (x + 2L) \left[ -\frac{\bar{T}_0}{EA_0} \right] + \left[ \frac{\bar{T}_0 L}{2EA_0} + \frac{\bar{T}_0 x}{2EA_0} \right] + \left[ \frac{2L\bar{T}_0}{EA_0} + \frac{3\bar{T}_0 x}{2EA_0} \right]$$

$$w(x) = (x + 2L) \left[ -\frac{\bar{T}_0}{EA_0} \right] + H_1(x + L) \left[ \frac{\bar{T}_0 L}{2EA_0} + \frac{\bar{T}_0 x}{2EA_0} \right] + H_2(x + 0) \left[ \frac{2L\bar{T}_0}{EA_0} + \frac{3\bar{T}_0 x}{2EA_0} \right]$$