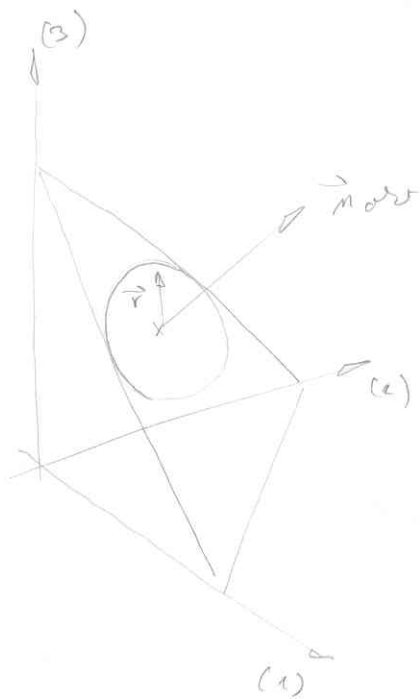


- ~~— Dokaz enakosti tangencialnih napetosti~~
- ~~— Airy-jeva funkcija~~
- ~~— Von-misesov pogoj tečenja~~
- ~~— Navier-lamillove enačbe~~
- ~~— Princip virtualnih pomikov~~
- ~~— Določitev modula plastičnosti~~
- ~~— Napetostno-deformacijske zveze v plastičnem področju~~
- ~~— Vpliv temperaturne obremenitve na kontinuum~~
- ~~— Ravnotežne enačbe mehanike~~
- ? — Dokaz enakosti tangencialnih napetosti
- ? — Vpliv temperaturne obremenitve na elastično telo
- Rotacijsko-simetrično delovanje napetostnega stanja — Airy-jeva funkcija ? ?
- ~~— Določitev modula plastičnosti~~
- ~~— Napetostno-deformacijske zveze v plastičnem področju~~
- Določitev modula elastičnosti
- Maxwellovo telo
- Zapis napetosti v oktaedrični ravnini
- Hookov zakon

KONTRASTNI ROČUL 9.5.

KONTRASTNA

ENAČBA



$$\vec{n} \times \vec{r} = \begin{vmatrix} e_1 & e_2 & e_3 \\ 1 & 1 & 1 \\ G_1 & G_2 & G_3 \end{vmatrix} \frac{\sqrt{3}}{3}$$

$$= \frac{\sqrt{3}}{3} \left[e_1(G_3 - G_2) - e_2(G_3 - G_1) + e_3(G_2 - G_1) \right]$$

$$|\vec{n} \times \vec{r}|^2 = r^2 \sin^2 90 = r^2$$

$$\frac{1}{3} \left[(G_3 - G_2)^2 + (G_3 - G_1)^2 + (G_2 - G_1)^2 \right] = r^2$$

za enaki dimeritveni primer:

$$G_0 = G_{02} = G_{0L} = G_{0Y}$$

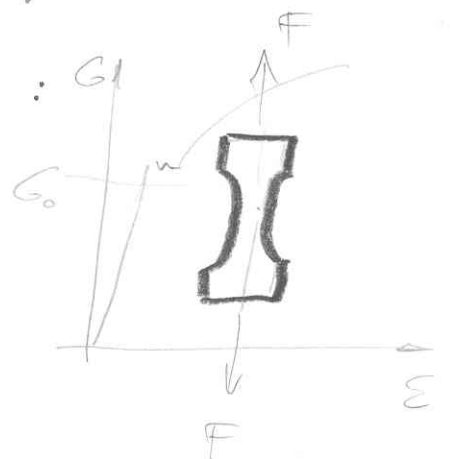
$$G_1 = G_0 \quad G_2 = G_3 = \emptyset$$

$$\frac{1}{3} \left[0^2 + G_0^2 + G_0^2 \right] = r^2$$

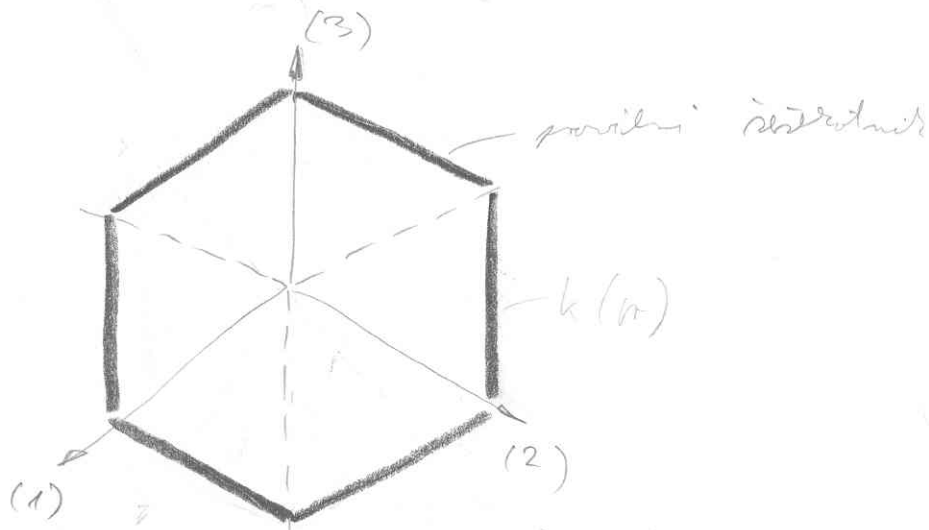
$$\frac{2}{3} G_0^2 = r^2 \Rightarrow \boxed{2G_0^2 = 3r^2}$$

$$\alpha(G_{ij}) = (G_1 - G_2)^2 + (G_2 - G_3)^2 + (G_3 - G_1)^2 = 2G_0$$

$$\boxed{\alpha(G_{ij}) \begin{matrix} < \\ \approx \\ > \end{matrix} 2G_0^2} \quad \begin{array}{l} \text{- elastično območje} \\ \text{- na meji platičnosti} \\ \text{- v eludoplastičnem območju} \end{array}$$



TRESCA - rina page: kancija



Enačba nateznosti

$$[(\sigma_1 - \sigma_2)^2 - k^2][(\sigma_2 - \sigma_3)^2 - k^2][(\sigma_3 - \sigma_1)^2 - k^2] = 0$$

$$(\sigma_1 - \sigma_2)^2 - k^2 = 0$$

$$(\sigma_2 - \sigma_3)^2 - k^2 = 0$$

$$(\sigma_3 - \sigma_1)^2 - k^2 = 0$$

Za enoosno napetostno stanje

$$\sigma_1 = \sigma_0$$

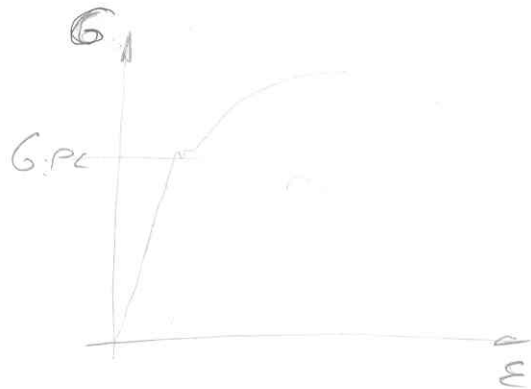
$$\sigma_2 = \sigma_3 = 0$$

$$(\sigma_1 - \sigma_2)^2 - \sigma_0^2 = 0$$

$$(\sigma_1 - \sigma_2) = \pm \sigma_0$$

$$(\sigma_2 - \sigma_3) = \pm \sigma_0$$

$$(\sigma_3 - \sigma_1) = \pm \sigma_0$$



$$\sigma_1 - \sigma_2 = \pm 2\sigma_3$$

$$\sigma_1 = \pm \frac{\sigma_1 - \sigma_2}{2}$$

$$\sigma_2 = \pm \frac{\sigma_2 - \sigma_3}{2}$$

$$\sigma_3 = \pm \frac{\sigma_3 - \sigma_1}{2}$$

ADR Y - jina funkcija

$$G_x = \frac{\partial^2 F}{\partial y^2}$$

$$G_y = \frac{\partial^2 F}{\partial x^2}$$

$$\Sigma_{xy} = -\frac{\partial^2 F}{\partial x \partial y} - xY - yX$$

$$\frac{\partial^2 \Sigma_{xy}}{\nu G_x G_y} = \frac{1}{E} \left[\frac{\partial^2 G_x}{\partial y^2} - \nu \frac{\partial^2 G_y}{\partial y^2} + \frac{\partial^2 G_y}{\partial x^2} - \nu \frac{\partial^2 G_x}{\partial x^2} \right] + \alpha \left[\frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial x^2} \right]$$

$$\nu = \frac{E}{2(1+\nu)}$$

$$-\frac{2(1+\nu)}{E} \frac{\partial^4 F}{\partial x^2 \partial y^2} = \frac{1}{E} \left[\frac{\partial^4 F}{\partial y^4} - \nu \frac{\partial^4 F}{\partial x^2 \partial y^2} + \frac{\partial^4 F}{\partial x^4} - \nu \frac{\partial^4 F}{\partial x^2 \partial y^2} \right] + \alpha \Delta T = 0$$

$$\left(\frac{\partial^4 F}{\partial x^4} + 2 \frac{\partial^4 F}{\partial x^2 \partial y^2} + \frac{\partial^4 F}{\partial y^4} \right) + \alpha E \Delta T = 0$$

$\Delta \Delta F$

$$\boxed{\Delta \Delta F + \alpha E \Delta T = 0}$$

$$\Delta [\Delta F + \alpha E T] = 0$$

za konstantnu temperaturu $\Delta T = 0 \Rightarrow \Delta \Delta F = 0$

Navier Lamé's equations

$$\sigma_{ij,j} + x_i = \phi$$

$$\sigma_{ij,j} [\varepsilon_{ij}(u_i)] + x_i = 0$$

$$\sigma_{ij} = 2\mu \varepsilon_{ij} + \lambda \varepsilon_{kk} \delta_{ij} - (2\mu + 3\lambda) \alpha T \delta_{ij}$$

$$\varepsilon_{ij} = \frac{1}{2} (\mu_{i,j} + \mu_{j,i})$$

$$\sigma_{ij,j} = 2\mu \varepsilon_{ij,j} + \lambda \varepsilon_{kk,j} \delta_{ij} - (2\mu + 3\lambda) \alpha \frac{T_{,i}}{T_{,j}} \delta_{ij}$$

$$\varepsilon_{ij,j} = \frac{1}{2} (\mu_{i,j,j} + \mu_{j,i,j})$$

$$\mu_{i,j,j} = \mu_{i,kk} = \sigma_{ii}$$

$$\mu_{i,j,j} = \mu_{j,i,j} = \frac{\partial}{\partial x_i} (\mu_{k,k})$$

$$\mu_{k,k} = \varepsilon_v$$

$$\varepsilon_v = \frac{\partial \mu_1}{\partial x_1} + \frac{\partial \mu_2}{\partial x_2} + \frac{\partial \mu_3}{\partial x_3} = \varepsilon_{11} + \varepsilon_{22} + \varepsilon_{33} = \mu_{k,k} = \varepsilon_{kk}$$

$$\mu_{j,i,j} = \varepsilon_{kk,i} = \varepsilon_{v,i}$$

$$\varepsilon_{ij,j} = \frac{1}{2} (\sigma_{ii} + \varepsilon_{v,i})$$

$$\mu (\sigma_{ii} + \varepsilon_{v,i}) + \lambda (\varepsilon_{v,i} - (2\mu + 3\lambda) \alpha T_{,i}) + X_i = 0$$

$$\boxed{\mu (\sigma_{ii} + \frac{\mu + \lambda}{\mu} \varepsilon_{v,i}) - (2\mu + 3\lambda) \alpha T_{,i} + X_i = 0}$$

$$x_i \left| \mu \left(\sigma_{ii} + \frac{\mu + \lambda}{\mu} \frac{\partial \varepsilon_v}{\partial x} \right) - (2\mu + 3\lambda) \alpha \frac{\partial T}{\partial x} + X = 0 \right.$$

$$y_i \left| \mu \left(\sigma_{ii} + \frac{\mu + \lambda}{\mu} \frac{\partial \varepsilon_v}{\partial y} \right) - (2\mu + 3\lambda) \alpha \frac{\partial T}{\partial y} + Y = 0 \right.$$

$$z_i \left| \mu \left(\sigma_{ii} + \frac{\mu + \lambda}{\mu} \frac{\partial \varepsilon_v}{\partial z} \right) - (2\mu + 3\lambda) \alpha \frac{\partial T}{\partial z} + Z = 0 \right.$$

Določitev modula plastičnosti

$$d\varepsilon_{ij}^{PL} = d\lambda \sigma_{ij}$$

$$d\varepsilon_{ij}^{PL} \cdot d\varepsilon_{ij}^{PL} = d\lambda^2 \sigma_{ij} \cdot \sigma_{ij}$$

deviator deformacij

$$\varepsilon_{ij} = \varepsilon_{ij} + \frac{\varepsilon_{kk}}{3} \delta_{ij}$$

$$\varepsilon_{ij}^{PL} = \varepsilon_{ij}^{PL} + \frac{\varepsilon_{kk}^{PL}}{3} \delta_{ij} \quad \varepsilon_{kk}^{PL} = 0$$

$$\varepsilon_{ij}^{PL} = 0 \Rightarrow \varepsilon_{ij}^{PL} = \varepsilon_{ij}^{PL}$$

$$\Rightarrow d\varepsilon_{ij}^{PL} = d\varepsilon_{ij}^{PL}$$

$$d\varepsilon_{ij}^{PL} d\varepsilon_{ij}^{PL} = d\lambda^2 \sigma_{ij} \cdot \sigma_{ij}$$

$$\sigma_{ij} \sigma_{ij} = 3 \sigma_{ort}^2$$

$$\varepsilon_{ij} \varepsilon_{ij} = 3 \gamma_{ort}^2$$

$$3 (d\gamma_{ort}^{PL})^2 = d\lambda^2 3 \sigma_{ort}^2$$

$$d\lambda = \frac{d\gamma_{ort}^{PL}}{\sigma_{ort}}$$

$$\sigma_{ort}^2 = \frac{1}{9} \left[(G_1 - G_2)^2 + (G_2 - G_3)^2 + (G_3 - G_1)^2 \right]$$

$D(G_{ij})$

$G_1 \neq 0$ $G_2 = G_3 = 0$ - osorno napetostno stanje

$$D(G_{ij}) = \frac{1}{9} [G_1^2 + G_1^2] = \frac{2}{9} G_1^2$$

$$\sigma_{ort} [G_{ij}] = \frac{\sqrt{2}}{3} G_1$$

Napetostno deformacijska raven v plastičnem področju

$$G_{ij} = -p \delta_{ij} + 2 \mu \dot{\epsilon}_{ij} - \frac{2}{3} \mu \dot{\epsilon}_v \delta_{ij}$$

$$G_{ij} = \sigma_{ij} + \frac{G_{kk}}{3} \delta_{ij}$$

$$-p = \frac{G_{kk}}{3}$$

$$G_{ij} = \sigma_{ij} + (-p \delta_{ij}) = -p \delta_{ij} + 2 \mu \dot{\epsilon}_{ij}^{PL} - \frac{2}{3} \mu \dot{\epsilon}_v^{PL} \delta_{ij}$$

$$\sigma_{ij} = 2 \mu \dot{\epsilon}_{ij}^{PL} = 2 \mu \frac{d\epsilon_{ij}^{PL}}{dt}$$

$$d\epsilon_{ij}^{PL} = \left(\frac{d\lambda}{2\mu} \right) \sigma_{ij} \quad \text{— razbit — venat — overa enota}$$

$d\lambda$ — modul plastičnosti.

$$\left(\begin{array}{ccc} d\epsilon_{11}^{PL}, d\epsilon_{12}^{PL} = \frac{1}{2} d\gamma_{12}^{PL}, d\epsilon_{13}^{PL} = \frac{1}{2} d\gamma_{13}^{PL} \\ \frac{1}{2} d\gamma_{21}^{PL}, d\epsilon_{22}^{PL} \\ \frac{1}{2} d\gamma_{31}^{PL}, \frac{1}{2} d\gamma_{32}^{PL}, d\epsilon_{23}^{PL} = \frac{1}{2} d\gamma_{23}^{PL} \\ d\epsilon_{33}^{PL} \end{array} \right) =$$

$$= d\lambda \left(\begin{array}{ccc} \frac{2G_{11} - G_{22} - G_{33}}{3} & G_{12} & G_{13} \\ G_{21} & \frac{2G_{22} - G_{11} - G_{33}}{3} & G_{32} \\ G_{31} & G_{32} & \frac{2G_{33} - G_{11} - G_{22}}{3} \end{array} \right)$$

$$d\epsilon_{11}^{PL} = \frac{2}{3} d\lambda [G_{11} - \frac{1}{2}(G_{22} + G_{33})]$$

$$\frac{1}{2} d\gamma_{12}^{PL} = d\lambda G_{12} \quad d\gamma_{12}^{PL} = 2 d\lambda G_{12}$$

$$\epsilon_{11} = \frac{1}{E} [G_{11} - \nu(G_{22} + G_{33})]$$

$$E_{PL} = \frac{3}{2 d\lambda} \quad \nu^{PL} = \frac{1}{2}$$

$$\frac{1}{E_{PL}} = \frac{2 d\lambda}{3}$$

Princip virtualnih pomika

Def: Virtualno delo ravnotežnega deformacijskega sistema je enaka nič.

$$W^z = W^u \quad / \delta$$

$$\delta W^z = \delta W^u$$

δu_i - virtualni pomiki i-te točke

$$G_{ij,j} + \delta g_i = \delta a_i$$

$$G_{ij,j} + \delta (g_i - a_i) = 0 \quad \text{- ravnotežna enačba za sive nove točke}$$

$$G_{ij,j} \delta u_i + \delta (g_i - a_i) \delta u_i = \phi$$

$$\left[\int_V [G_{ij,j} \delta u_i + \delta (g_i - a_i) \delta u_i] dV = \phi \right] \quad \text{ravnotežna enačba}$$

$$G_{ij,j} \delta u_i = (G_{ij} \delta u)_{,j} - G_{ij} \delta u_{i,j}$$

$$\delta u_{i,j} = \delta \epsilon_{ij} = \delta \epsilon_{ij} + \delta \omega_{ij} \quad \text{translacijska rotacijska}$$

$$G_{ij} \delta u_{i,j} = G_{ij} (\delta \epsilon_{ij} + \delta \omega_{ij})$$

$$= G_{ij} \delta \epsilon_{ij} + \underbrace{G_{ij} \delta \omega_{ij}}_0$$

$$[G_{ij} \delta u_{i,j} = G_{ij} \delta \epsilon_{ij}]$$

$$G_{ij,j} = (G_{ij} \delta u)_{,j} - G_{ij} \delta \epsilon_{ij}$$

Vzpliv temperature obrnitev na kontinuum

EVACIJA ZA VEZAVO TERMODINAMSKO >TAUJE

$$\rho_0 T + \frac{Q}{S_{CE}} = \frac{d}{dt} \left(T + \frac{m}{S_{CE}} T_0 \epsilon_v \right)$$

α - temperatni koeficient

T - razlika temperature

$$T = (T_2 - T_1)$$

$T > 0$ segrevanje

$T < 0$ ohlajanje

κ - koeficient konduktivnosti

Q - notranja generacija toplote

S - gostota

C_e - specifična toplota na enoto volumna pri konstantni specifični deformaciji

T_0 - temperatura mišični pri robenih deformacij

m - masa

ϵ_v - plastifikacija materiala

$$\frac{\sigma_{ij}}{H} = \frac{1}{2\nu} \sigma_{ij} - \frac{\nu}{E} \sigma_{kk} \delta_{ij} = \epsilon_{ij}^{pi}$$

$$\epsilon_{ij}^T = \alpha T \delta_{ij} \rightarrow \epsilon_{ij}^{cal} = \epsilon_{ij}^{ip} + \epsilon_{ij}^T - \epsilon_{ij}$$

$$\epsilon_{ij} = \frac{1}{2} \nu \sigma_{ij} - \left(\frac{\nu}{E} \sigma_{kk} - \alpha T \right) \delta_{ij}$$

$$\sigma_{ij} = 2\mu \epsilon_{ij} + 2\mu \left(\frac{\nu}{E} \sigma_{kk} - \alpha T \right) \delta_{ij}$$

$$\underbrace{\sigma_{ij} \delta_{ij}}_{\sigma_{kk}} = 2\mu \underbrace{\epsilon_{ij} \delta_{ij}}_{\epsilon_{kk}} + 2\mu \left(\frac{\nu}{E} \sigma_{kk} - \alpha T \right) \underbrace{\delta_{ij} \delta_{ij}}_3$$

$$\sigma_{kk} \left(1 - 2\nu \frac{\nu^3}{E} \right) = 2\mu \epsilon_{kk} - 6\mu \alpha T$$

$$1 - \frac{2E}{2(1+\nu)} \frac{3\nu}{E} = \frac{1+\nu-3\nu}{(1+\nu)} = \frac{1-2\nu}{1+\nu}$$

$$\sigma_{kk} \frac{1-2\nu}{(1+\nu)} = \frac{2E}{2(1+\nu)} \epsilon_{kk} - \frac{3\nu E}{2(1+\nu)} \alpha T$$

$$\boxed{\sigma_{kk} = \frac{E}{1-2\nu} \epsilon_{kk} - \frac{3E}{1-2\nu} \alpha T}$$

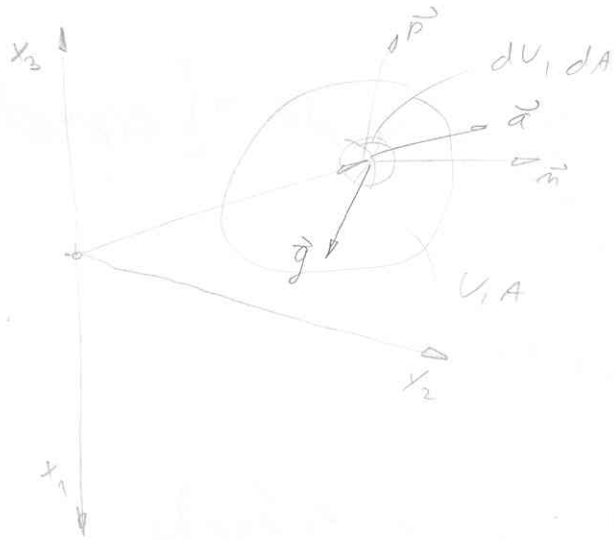
$$2\mu \frac{\nu}{E} \sigma_{kk} = \frac{2E}{2(1+\nu)} \frac{E}{(1-2\nu)} \epsilon_{kk} - 3\lambda \alpha T$$

$$\boxed{\sigma_{ij} = 2\mu \epsilon_{ij} + \lambda \epsilon_{kk} \delta_{ij} - (2\mu + 3\lambda) \alpha T \delta_{ij}}$$

$$\sigma_{kk} = \frac{E}{1+2\nu} \epsilon_{kk} - \frac{3E}{1-2\nu} \alpha T$$

Površina

masa m



$$\vec{n} = \frac{\nabla \phi}{|\nabla \phi|}$$

$$\phi(x_1, x_2, x_3) = 0 \quad \vec{r} = (x_1, x_2)$$

$$p_i = G_{ij} m_j$$

RAVNOTEŽNA SILA

$$1.) \sum \vec{F}_i = \vec{0}$$

$$2.) \sum \vec{\pi}_i = \vec{0}$$

$$2.) \sum \vec{F}_i \times \vec{r}_i = \vec{0}$$

DUŠIČNA SILA

$$p = a \cdot F$$

VSOTA VSEH SILA = 0

$$\int_A p_i dA = \int_A G_{ij} m_j dA$$

$$p_i = G_{ij} m_j = \int_V G_{ij, j} dV$$

$$\int_V [G_{ij, j} + S(g_i - a_i)] dV = 0$$

RAVNOTEŽNA ENAČBA SILA NA CELOTUEN TELESU

Kompresijski modul

$$G_{ij}^k = \frac{G_{kk}}{3} \delta_{ij} = -p \delta_{ij}$$

$$G_1 = G_2 = G_3 = -p$$

$$T = 0$$

$$\epsilon_{kk} = \frac{1-2\nu}{E} G_{kk} = -p \frac{1}{\frac{E}{3(1-2\nu)}}$$

KOMPRESIJSKI MODUL

$$\epsilon_{kk} = \epsilon_v = \frac{-p}{K}$$

$K \rightarrow \infty \rightarrow \epsilon_v \rightarrow 0$ - to pomeni da je telo idealno teko

$$\lim_{\nu \rightarrow \frac{1}{2}} \frac{E}{3(1-2\nu)} = \lim_{K \rightarrow \infty} K \rightarrow \infty$$

$$\lim_{\nu \rightarrow \frac{1}{2}} \epsilon_v \rightarrow 0$$

$$\nu \rightarrow \frac{1}{2} \quad \epsilon_v^{PL} \rightarrow 0$$

$$\epsilon_v^{CEL} = \epsilon_v^{EL} + \epsilon_v^{PL}$$